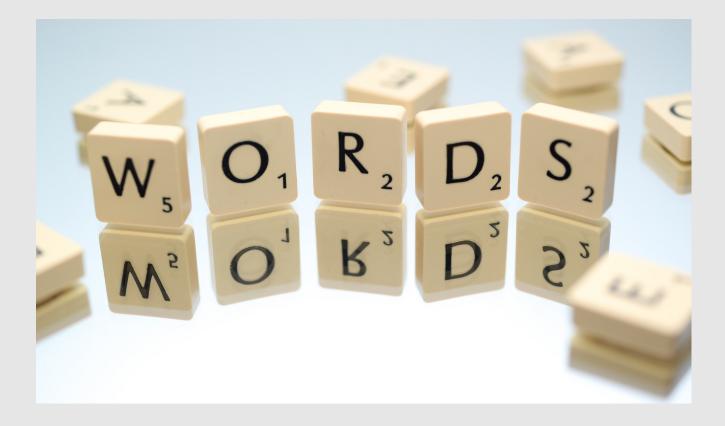


Hidden Markov Models and Language Modeling with N-Grams

> Natalie Parde UIC CS 421

Language is inherently contextual.



- Words or characters in language are dependent upon one another!
- Sequence modeling allows us to make use of sequential information in language
- There are many ways to implement sequence models, including but not limited to:
 - Hidden Markov models
 - Neural networks

What are Hidden Markov Models (HMMs)?

- Probabilistic generative models for sequences
- Make predictions based on an underlying set of hidden states



How does sequence labeling differ from other types of classification?

 Other types of classification: Often classify entire text samples into discrete, predefined groups

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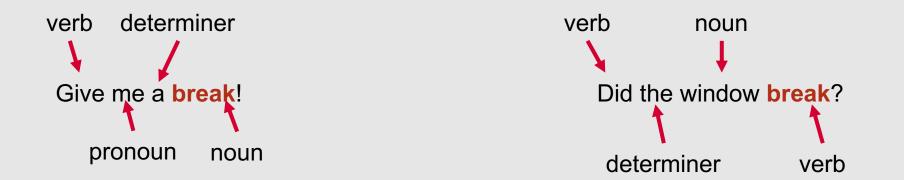
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In these scenarios, models assume that the individual datapoints being classified are disconnected and independent.

- Many NLP problems do not satisfy this assumption
- Often problems involve:
 - Interconnected decisions
 - Each of which are mutually dependent
 - Each of which resolve different ambiguities
- For these problems, different learning and inference techniques are needed!

Sequence Labeling

- One example: sequence labeling tasks.
- Objective: Find the label for the next item, based on the labels of other items in the sequence.



Example Sequence Labeling Applications

- Named entity recognition
- Semantic role labeling

person

organization

Natalie Parde works at the University of Illinois at Chicago and lives in Chicago, Illinois.

location

agent

source destination

Natalie drove for 15 hours from **Dallas** to **Chicago** in her hail-damaged **Honda Accord**.

instrument

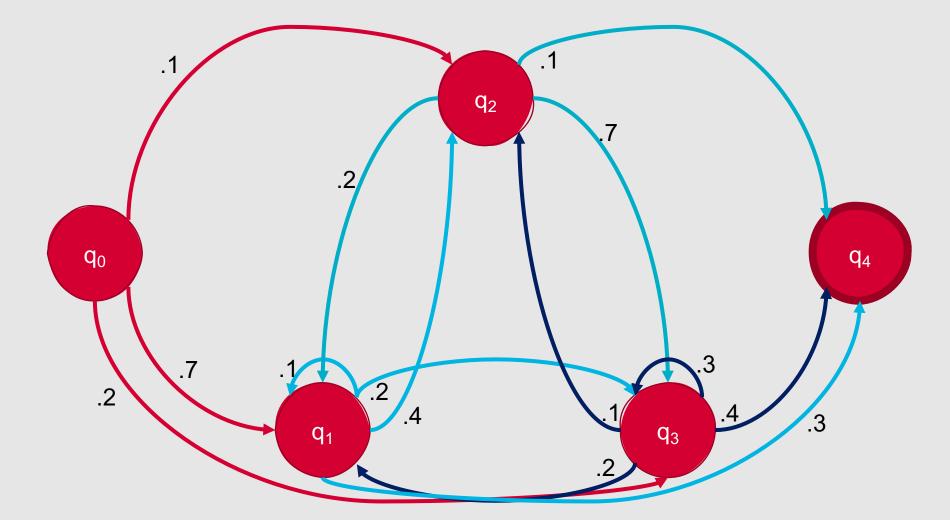
Probabilistic Sequence Models

- Resolving uncertainties involves multiple, interdependent classifications
- Two standard models:
 - Hidden Markov Models
 - Conditional Random Fields

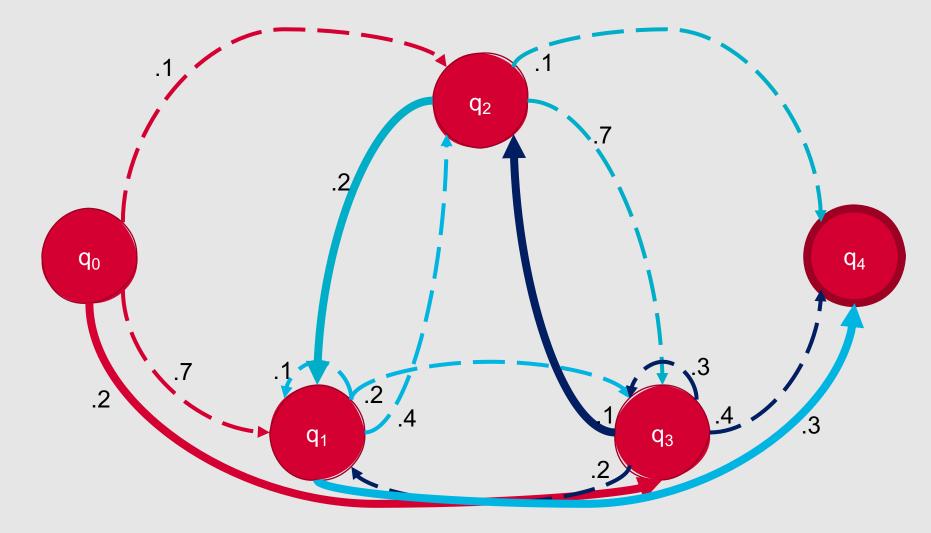
What are Markov Models?

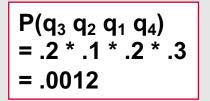
- Finite state automata with probabilistic state transitions
- Markov Property: The future is independent of the past, given the present.
 - In other words, the next state only depends on the current state ... it is independent of previous history.
- Also referred to as Markov Chains

Sample Markov Model



Sample Markov Model

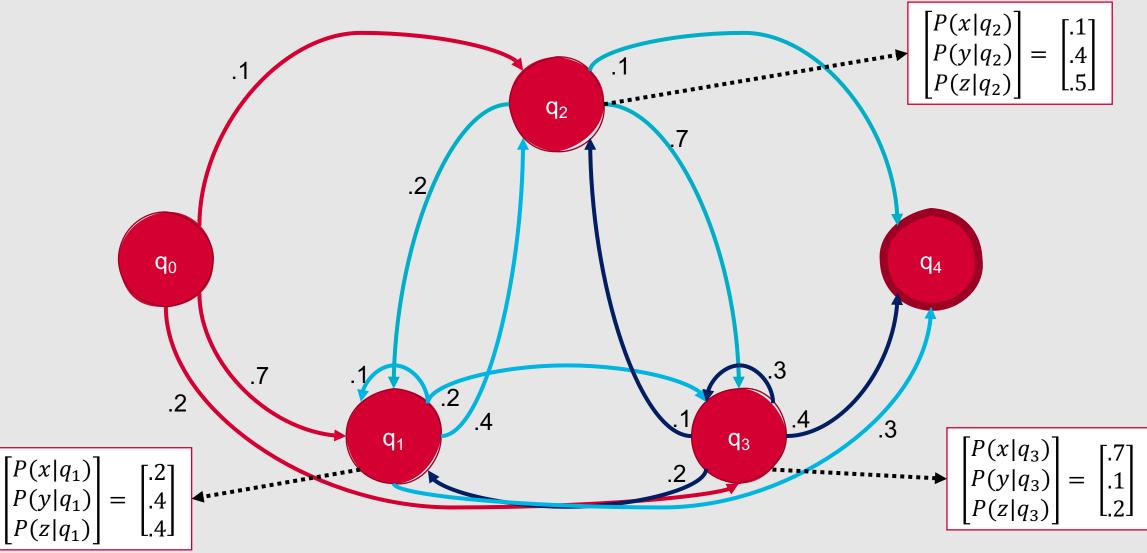




Hidden Markov Models

- Probabilistic generative models for sequences
- Assume an underlying set of hidden (unobserved) states in which the model can be
- Assume probabilistic transitions between states over time
- Assume probabilistic generation of items (e.g., tokens) from states

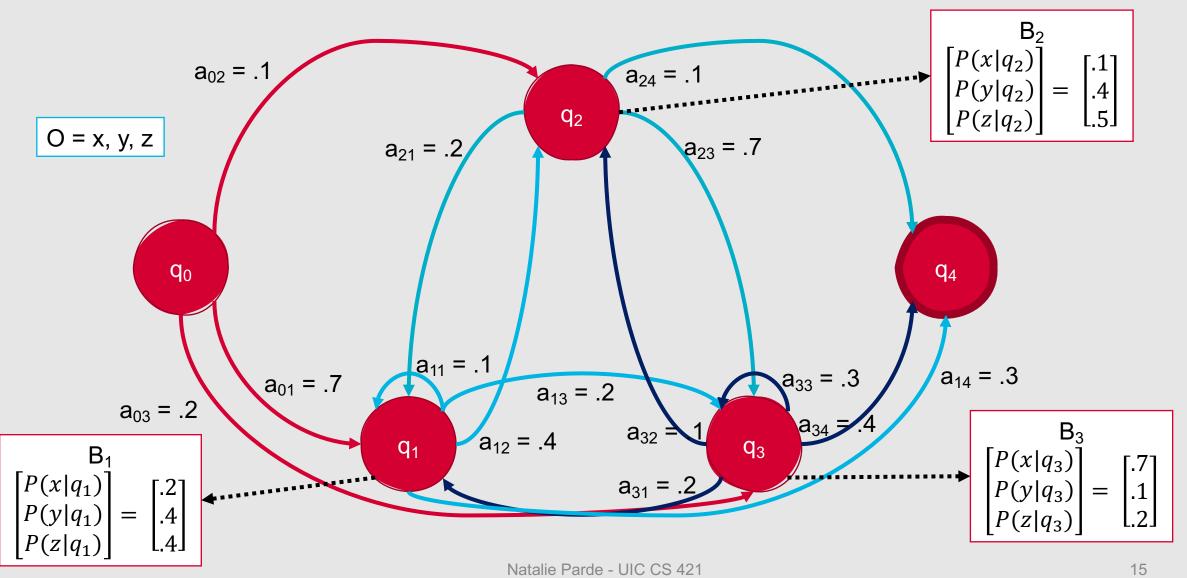
Sample Hidden Markov Model



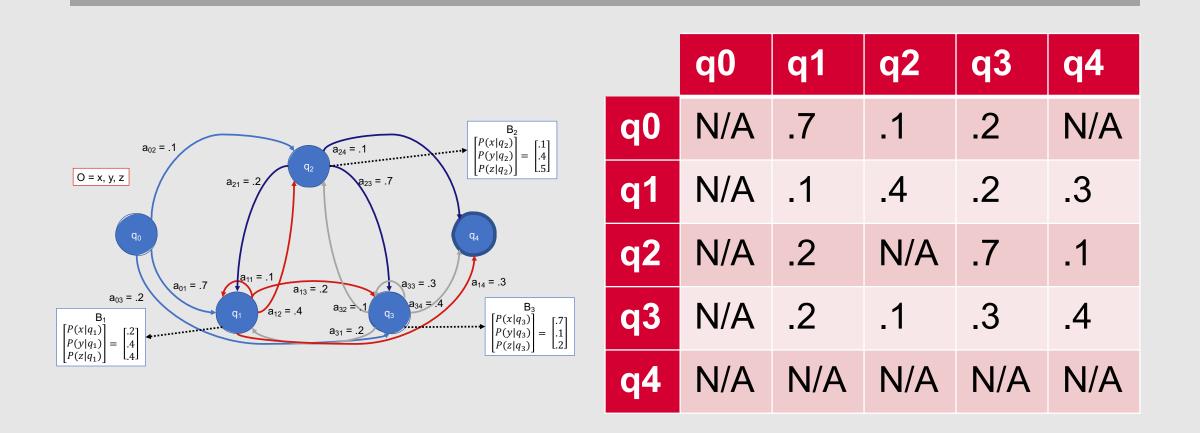
Formal Definition

- A Hidden Markov Model can be specified by enumerating the following properties:
 - The set of states, Q
 - A transition probability matrix, *A*, where each a_{ij} represents the probability of moving from state *i* to state *j*, such that ∑ⁿ_{i=1} a_{ij} = 1 ∀*i*
 - A sequence of T observations, O, each drawn from a vocabulary V = v₁, v₂, ..., v_V
 - A sequence of observation likelihoods, *B*, also called emission probabilities, each expressing the probability of an observation o_t being generated from a state *i*
 - A start state, *q₀*, and final state, *q_F*, that are not associated with observations, together with transition probabilities out of *q₀* and into *q_F*

Sample Hidden Markov Model



Corresponding Transition Matrix



Practical Applications of HMMs

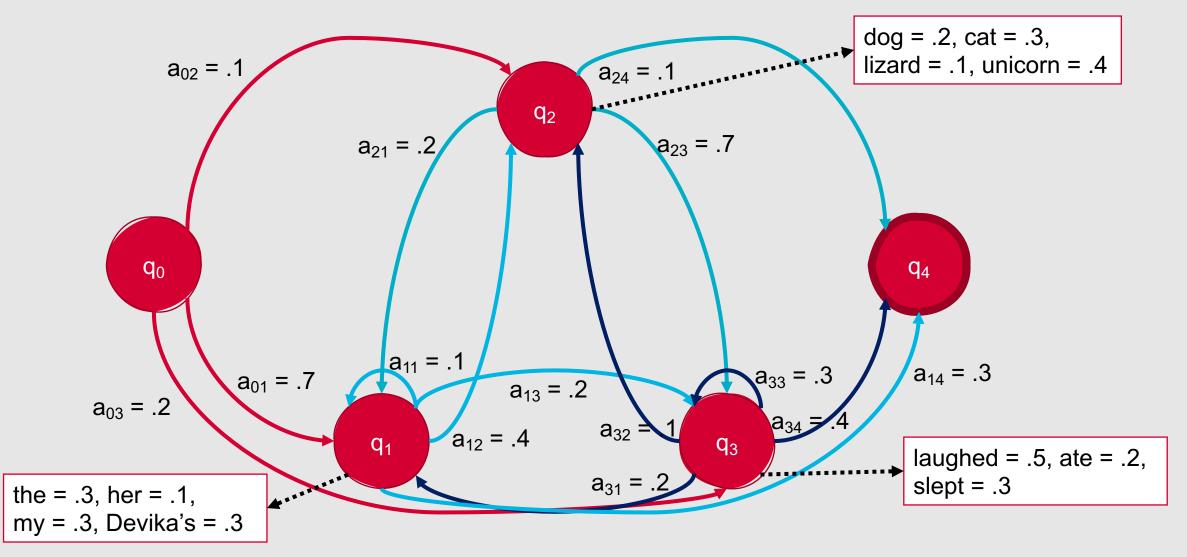
- One intuitive application: Text generation
- More generally, you can generate a sequence of T observations: O = o₁, o₂, ..., o_T

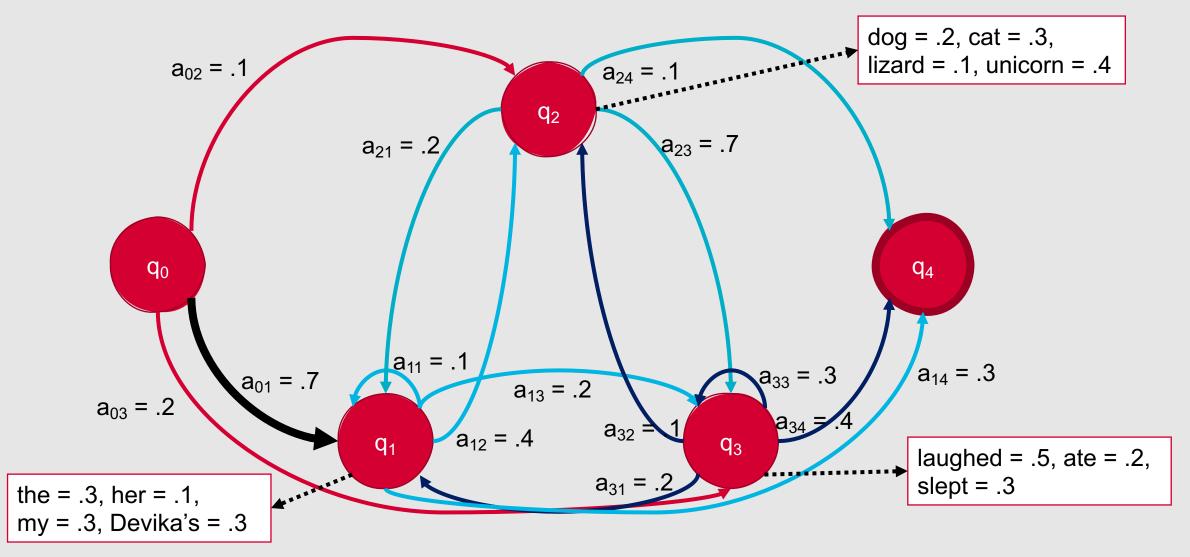
Begin in the start state

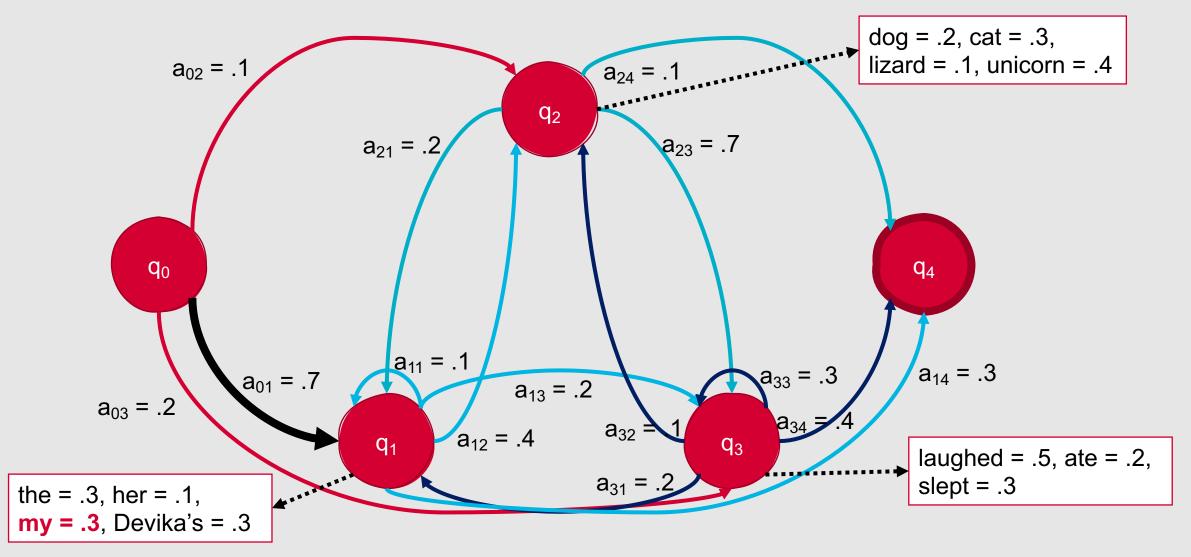
For t in [0, ..., T]:

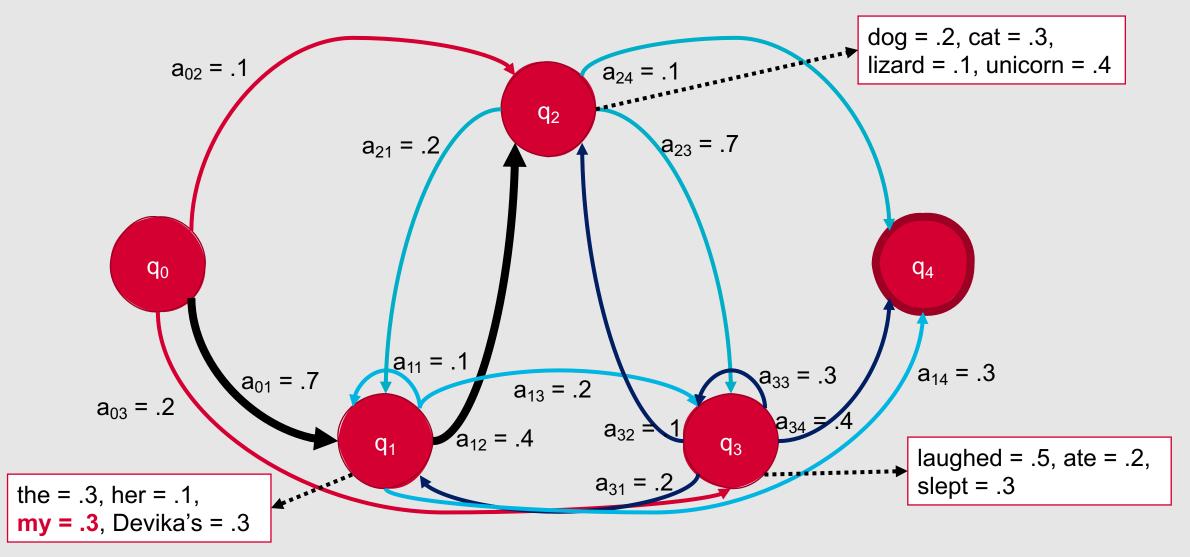
Randomly select a new state based on the transition distribution for the current state

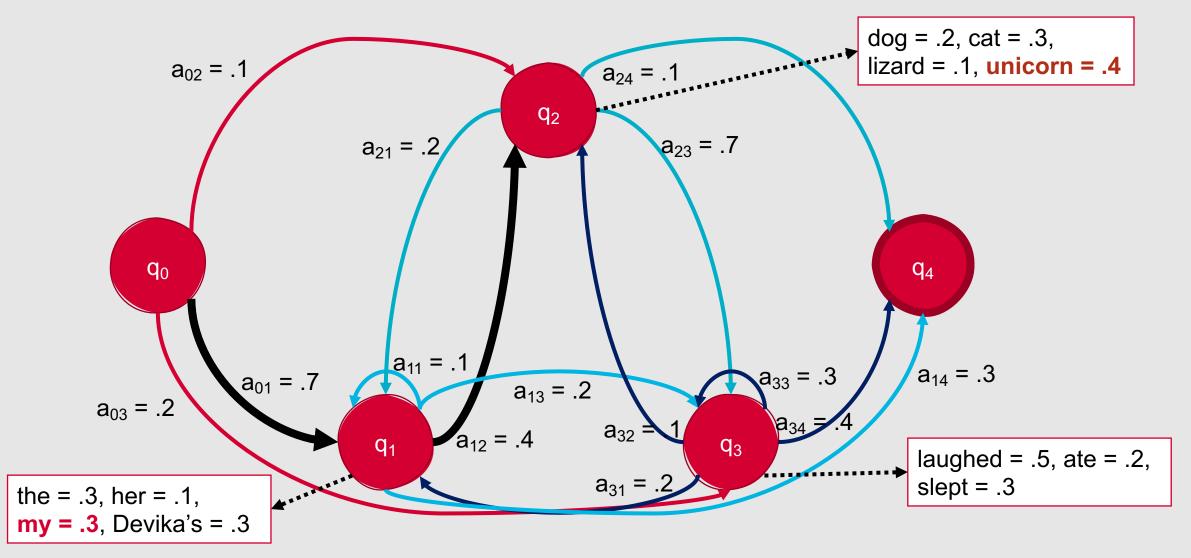
Randomly select an observation from the new state based on the observation distribution for that state

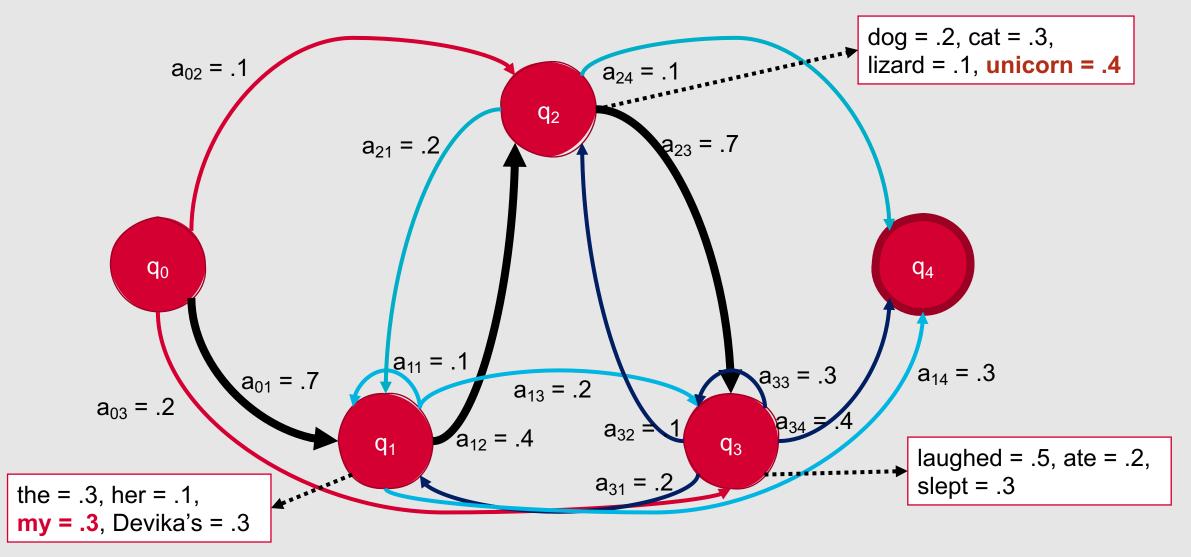


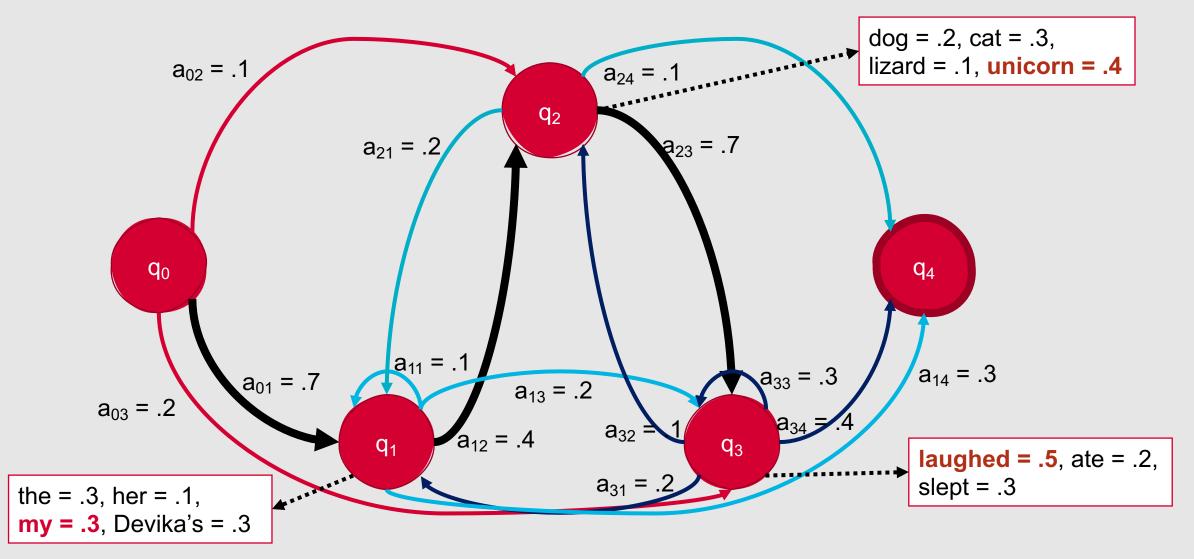


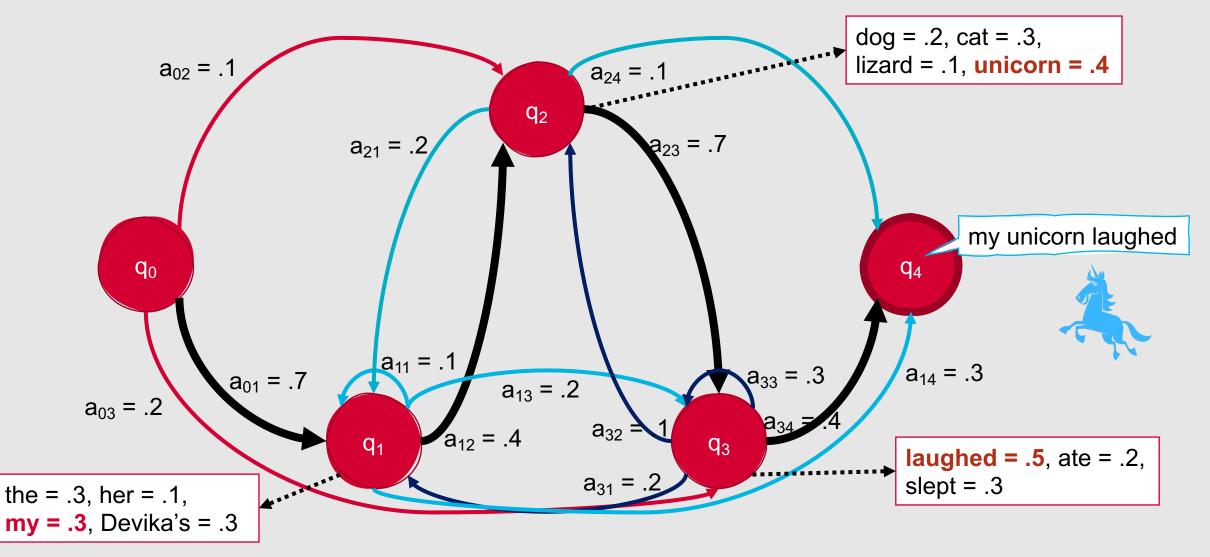








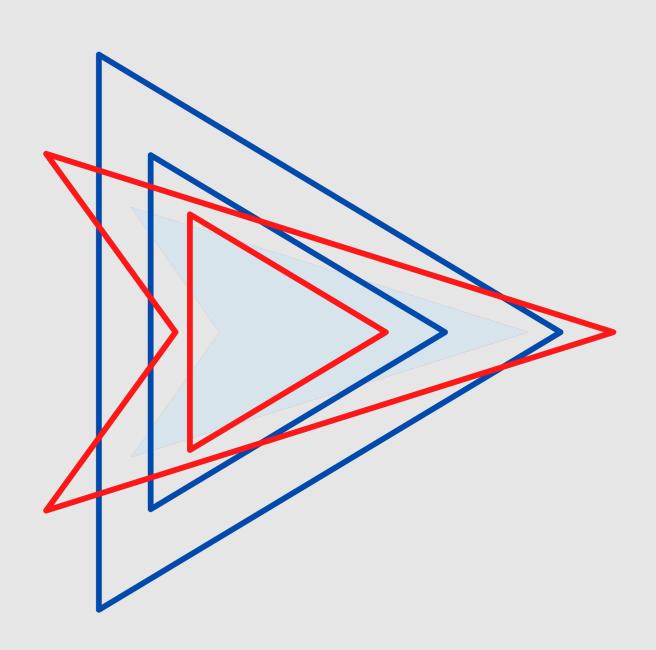




Three Fundamental HMM Problems

- Observation Likelihood: How likely is a particular observation sequence to occur?
- Decoding: What is the best sequence of hidden states for an observed sequence?
 - What is the best sequence of labels for our test data?
- Learning: What are the transition probabilities and observation likelihoods that best fit the observation sequence and HMM states?
 - How do we empirically fit our training data?

One way to compute observation likelihood is by using forward probabilities.



Observation Likelihood

- Given a sequence of observations and an HMM, what is the probability that this sequence was generated by the model?
- Useful for two tasks:
 - Sequence
 classification
 - Selecting the most likely sequence

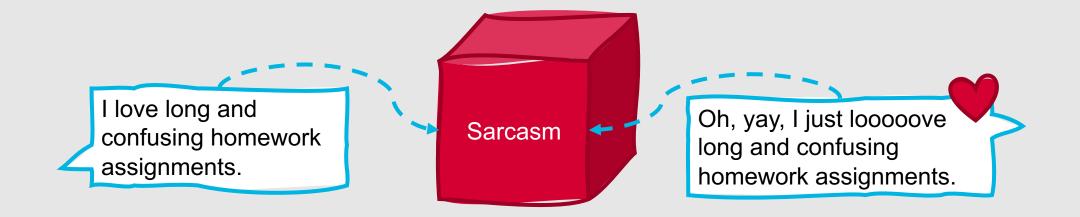
Sequence Classification

- Assuming an HMM is available for every possible class, what is the most likely class for a given observation sequence?
 - Which HMM is most likely to have generated the sequence?



Most Likely Sequence

• Of two or more possible sequences, which one was most likely generated by a given HMM?



How can we compute the observation likelihood?

- Naïve Solution:
 - Consider all possible state sequences, Q, of length T that the model, λ , could have traversed in generating the given observation sequence, O
 - Compute the probability of a given state sequence from A, and multiply it by the probability of generating the given observation sequence for that state sequence
 - $P(O,Q \mid \lambda) = P(O \mid Q, \lambda) * P(Q \mid \lambda)$
 - Repeat for all possible state sequences, and sum over all to get $P(O \mid \lambda)$
- But, this is computationally complex!
 - $O(TN^T)$

How can we compute the observation likelihood?

• Efficient Solution:

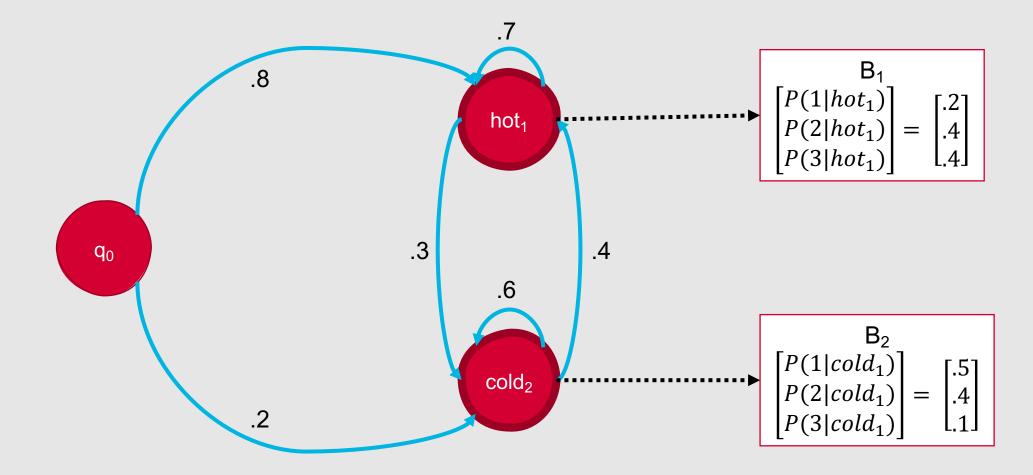
- Forward Algorithm: Dynamic programming algorithm that computes the observation probability by summing over the probabilities of all possible hidden state paths that could generate the observation sequence.
- Implicitly folds each of these paths into a single forward trellis
- Why does this work?
 - Markov assumption (the probability of being in any state at a given time *t* only relies on the probability of being in each possible state at time *t*-1).
- Works in O(TN²) time!



Sample Problem

- It is 2799 and you are a climatologist studying the history of global warming
- Unfortunately, you have no official records of the weather in Baltimore for the summer of 2007, although you know some key weather patterns, which you're representing using HMMs
- Fortunately, a major breakthrough occurs: you find Jason Eisner's diary, which lists how many ice cream cones he ate every day that summer
- You decide to focus on a three-day sequence:
 - Day 1: 3 ice cream cones
 - Day 2: 1 ice cream cone
 - Day 3: 3 ice cream cones

Current Leading HMM



How do you compute your forward probabilities?

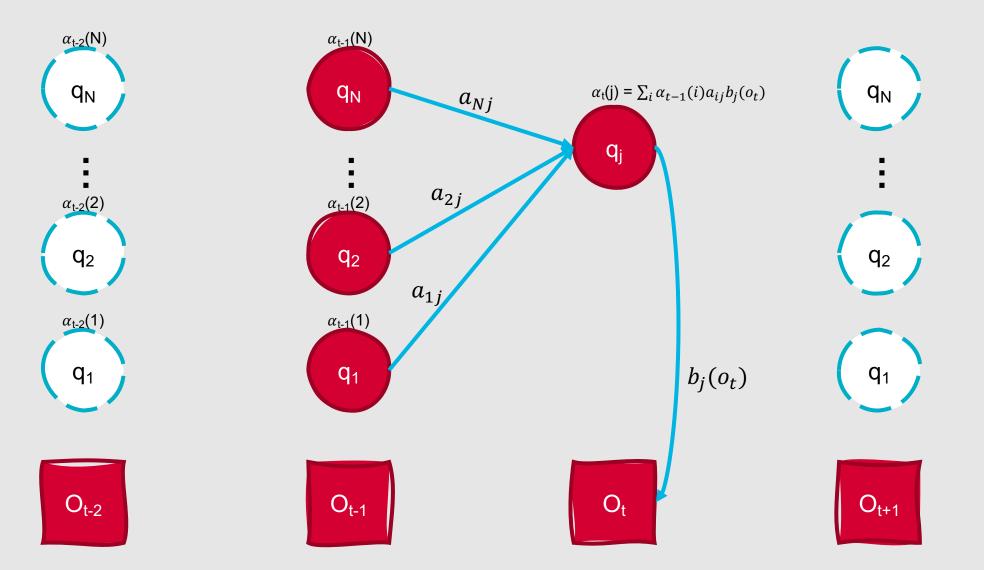
- Let $\alpha_i(j)$ be the probability of being in state *j* after seeing the first *t* observations, given your HMM λ
- α_i(j) is computed by summing over the probabilities of every path that could lead you to this cell
 - $\alpha_i(j) = P(o_1, o_2 \dots o_t, q_t = j | \lambda) = \sum_{i=1}^N \alpha_{t-1}(i) a_{ij} b_j(o_t)$
 - $q_t = j$ is the probability that the t^{th} state in the sequence of states is state j
 - $\alpha_{t-1}(i)$: The previous forward path probability from the previous time step
 - a_{ij} : The transition probability from previous state q_i to current state q_j
 - $b_j(o_t)$: The state observation likelihood of the observed item o_t given the current state j

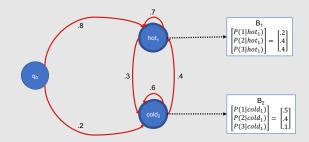
Formal Algorithm

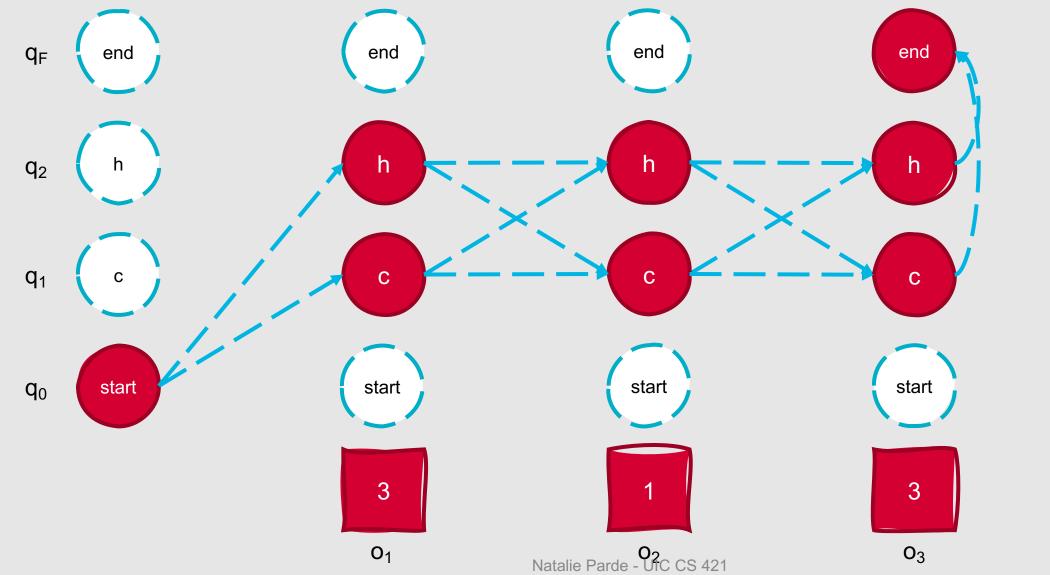
create a probability matrix forward[N+2,T]

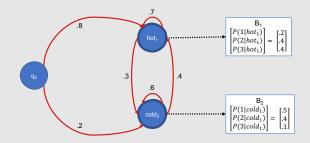
for each state q in [1, ..., N] do: forward[q,1] $\leftarrow a_{0,q} * b_q(o_1)$ for each time step t from 2 to T do: for each state q in [1, ..., N] do: forward[q,t] $\leftarrow \sum_{q'=1}^{N} forward[q',t-1] * a_{q',q} * b_q(o_t)$ forwardprob $\leftarrow \sum_{q=1}^{N} forward[q,T]$

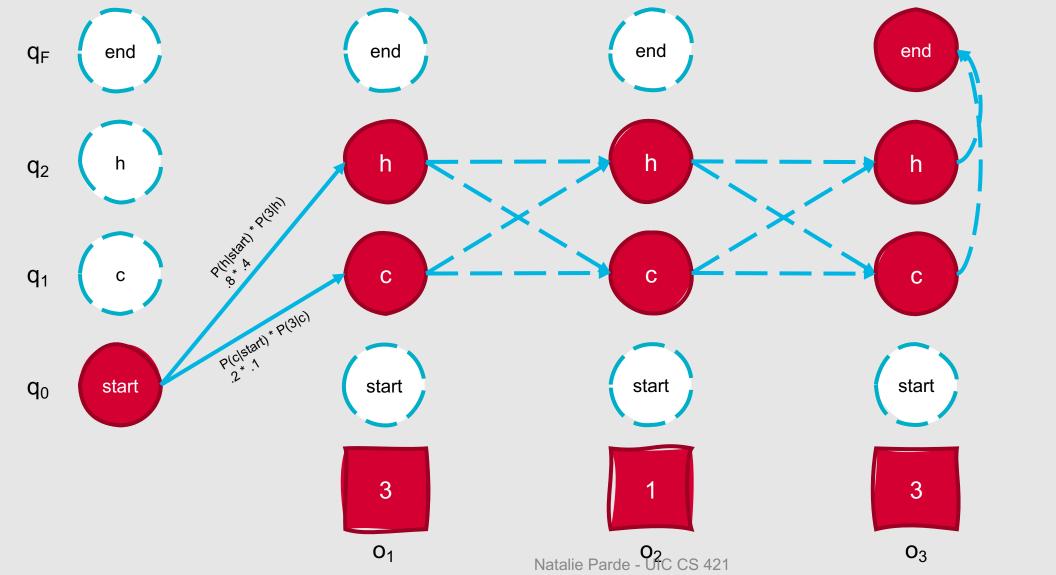
Forward Step

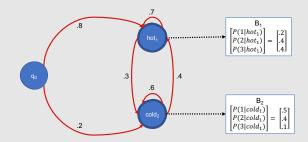


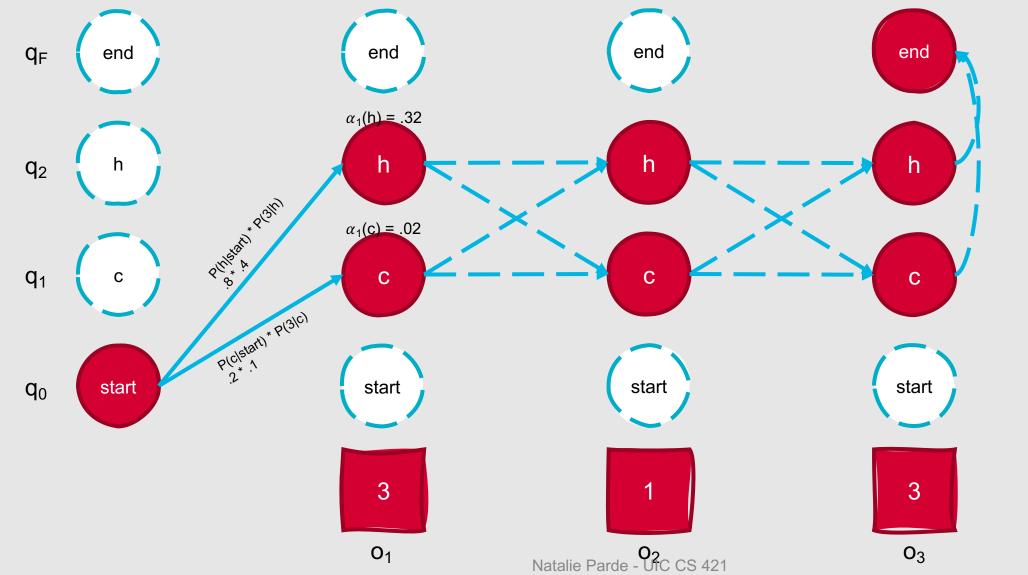


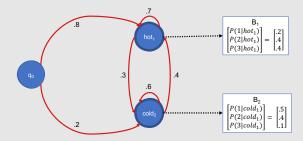


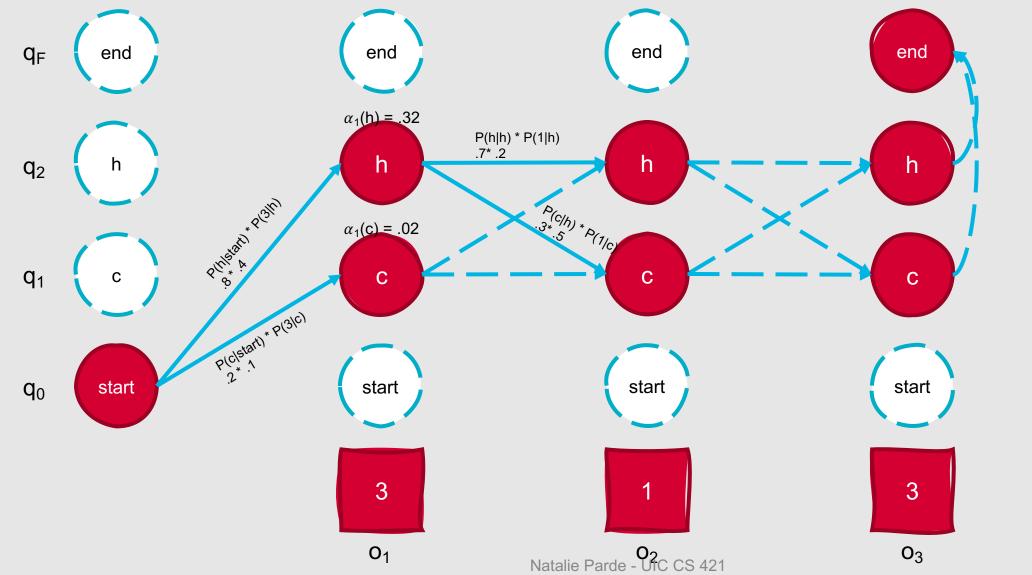


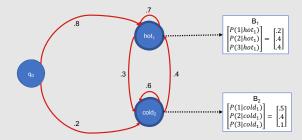


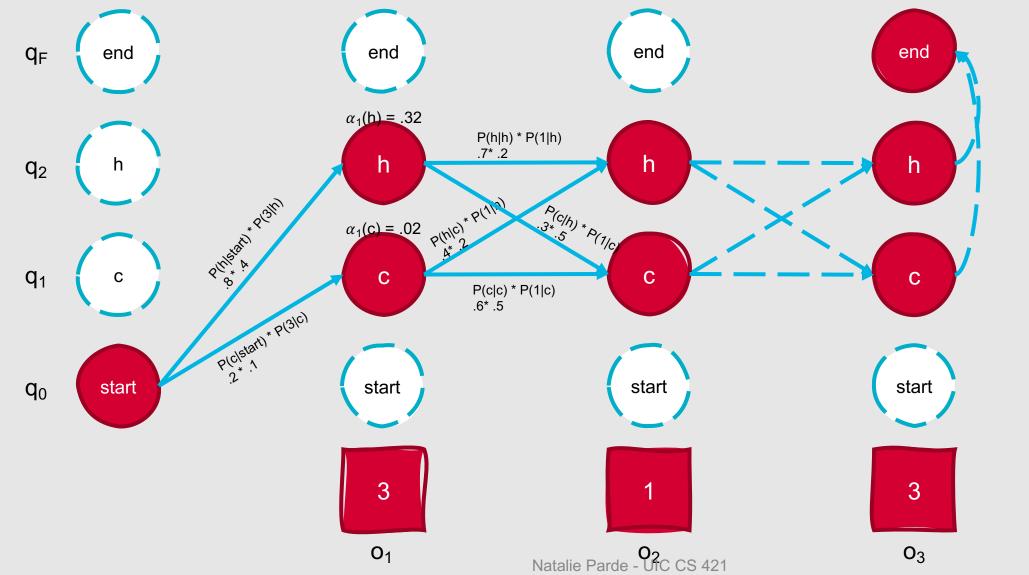


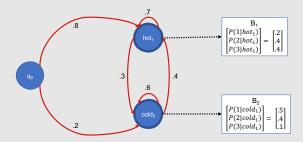


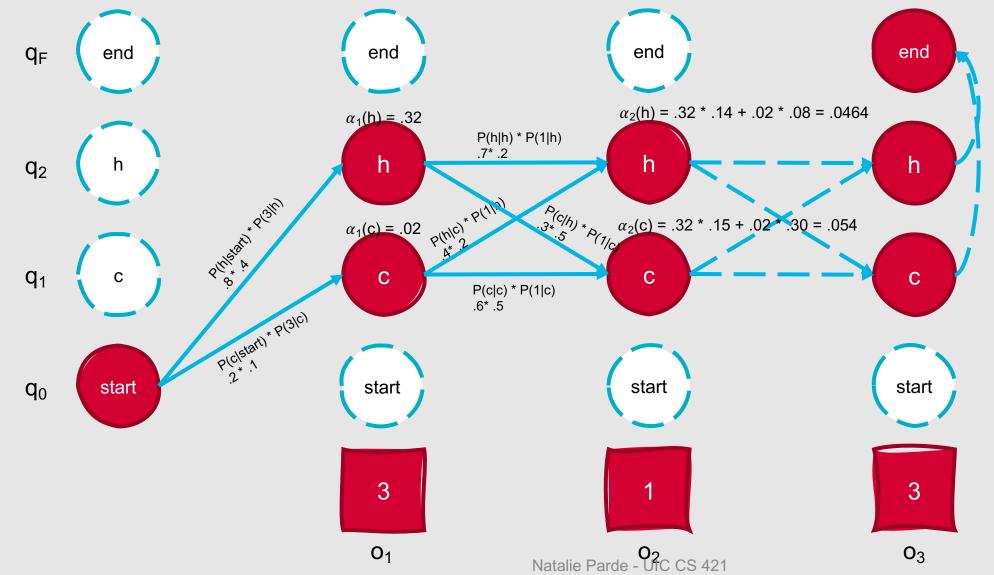


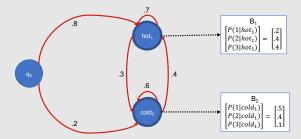


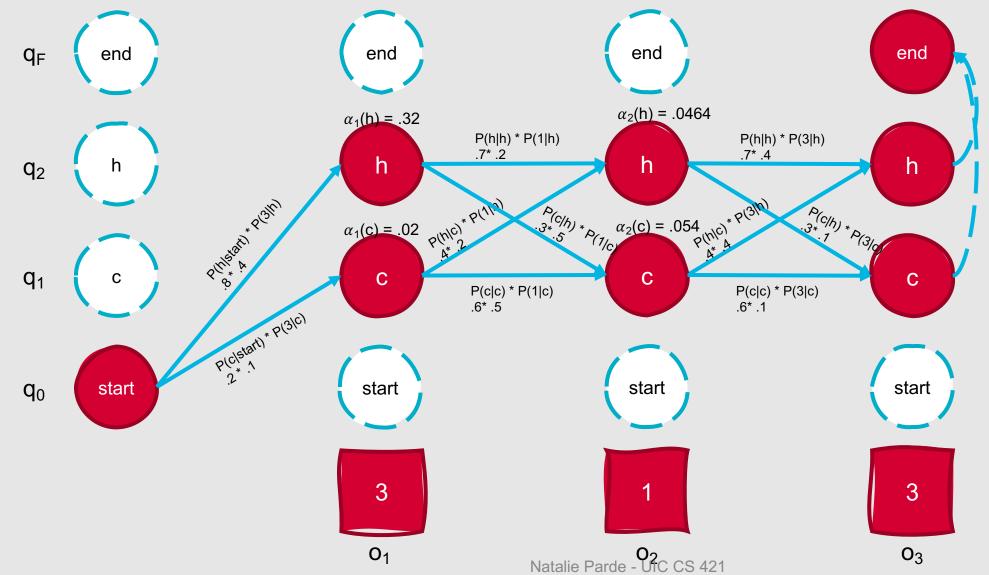


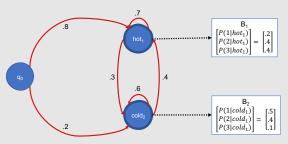


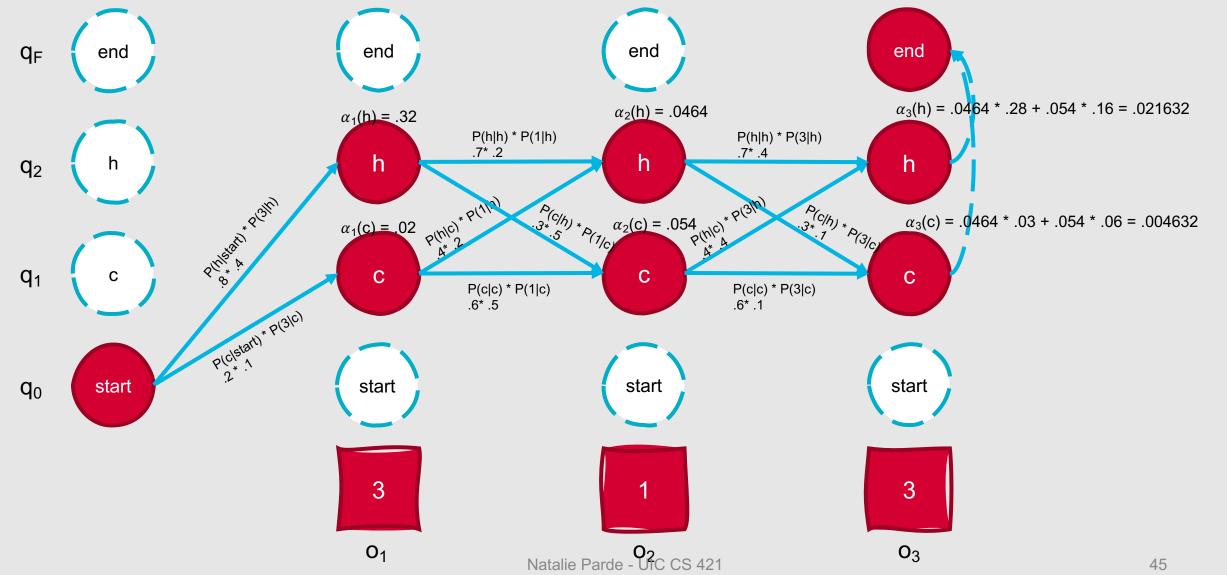


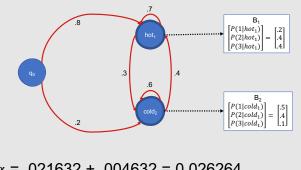


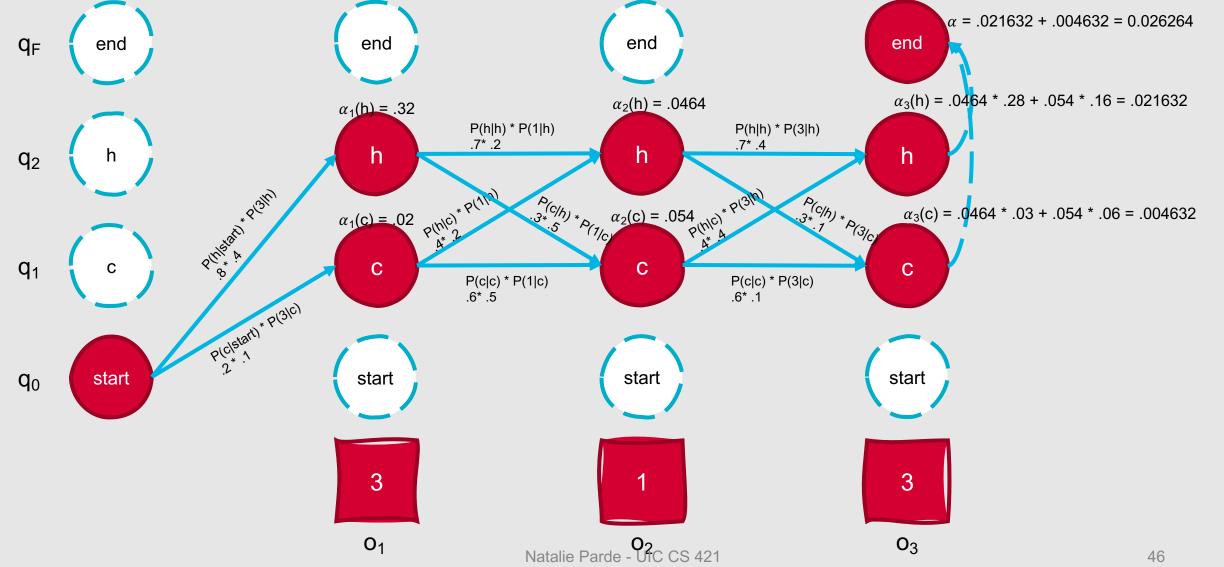












We've so far tackled one of the fundamental HMM tasks.

- What is the probability that a sequence of observations fits a given HMM?
- However, there are still two remaining tasks to explore....

Decoding

- Given an observation sequence and an HMM, what is the best hidden state sequence?
 - How do we choose a state sequence that is optimal in some sense (e.g., best explains the observations)?
- Very useful for sequence labeling!



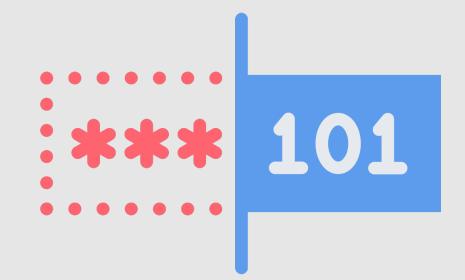
Decoding

- Naïve Approach:
 - For each hidden state sequence Q, compute P(O|Q)
 - Pick the sequence with the highest probability
- However, this is computationally inefficient!
 - $O(N^T)$

How can we decode sequences more efficiently?

Viterbi Algorithm

- Another dynamic programming algorithm
- Uses a similar trellis to the Forward algorithm
- Viterbi time complexity: O(N²T)



Viterbi Intuition

- Goal: Compute the joint probability of the observation sequence together with the best state sequence
- So, recursively compute the probability of the most likely subsequence of states that accounts for the first t observations and ends in state q_i.

$$v_t(j) = \max_{q_0, q_1, \dots, q_{t-1}} P(q_0, q_1, \dots, q_{t-1}, o_1, \dots, o_t, q_t = q_j | \lambda)$$

- Also record backpointers that subsequently allow you to backtrace the most probable state sequence
 - bt_t(j) stores the state at time t-1 that maximizes the probability that the system was in state q_i at time t, given the observed sequence

Formal Algorithm

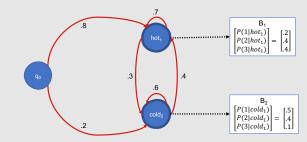
create a path probability matrix Viterbi[N+2,T]

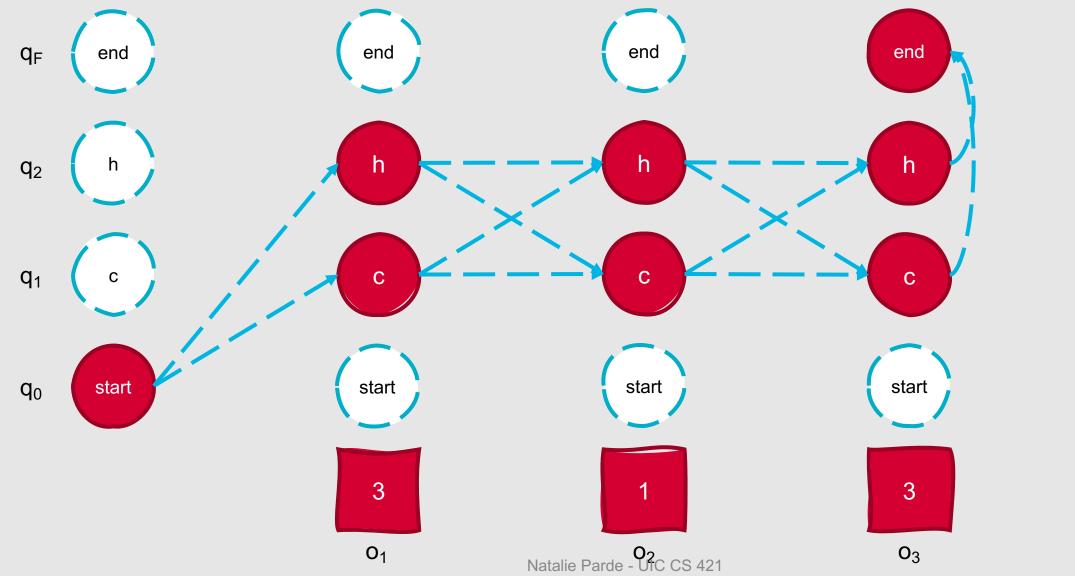
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for each state q in [1,...,N] do:
          Viterbi[q,1] \leftarrow a_{0,q} * b_q(o_1)
          backpointer[q,1] \leftarrow 0
for each time step t in [2,...,T] do:
          for each state q in [1,...,N] do:
                    viterbi[q,t] \leftarrow \max_{q' \in [1,\dots,N]} viterbi[q',t-1] * a_{q',q} * b_q(o_t)
                    backpointer[q,t] \leftarrow argmax \ viterbi[q',t-1] * a_{q',q} * b_q(o_t)
                                            a' \in [1,...,N]
bestpathprob \leftarrow \max_{q' \in [1,...,N]} viterbi[q',T]
bestpathpointer \leftarrow \operatorname{argmax} viterbi[q', T]
                            q' \in [1, ..., N]
```

Seem familiar?

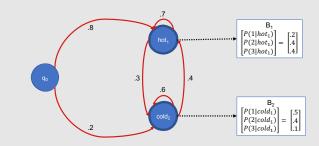
 Viterbi is basically the forward algorithm + backpointers, and substituting a max function for the summation operator

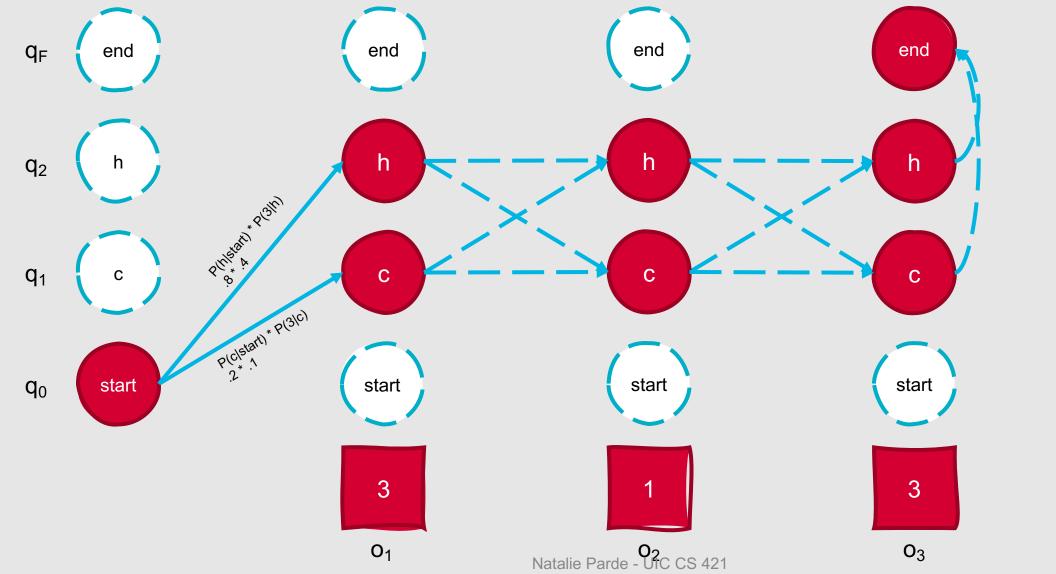


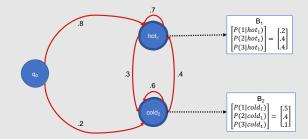


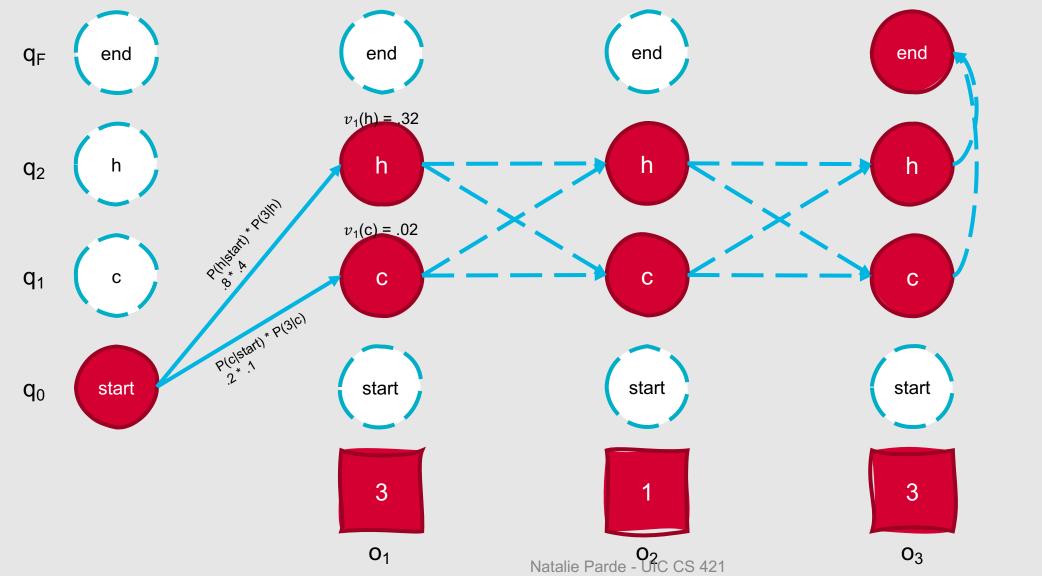


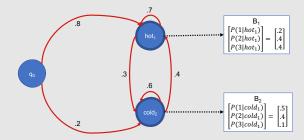


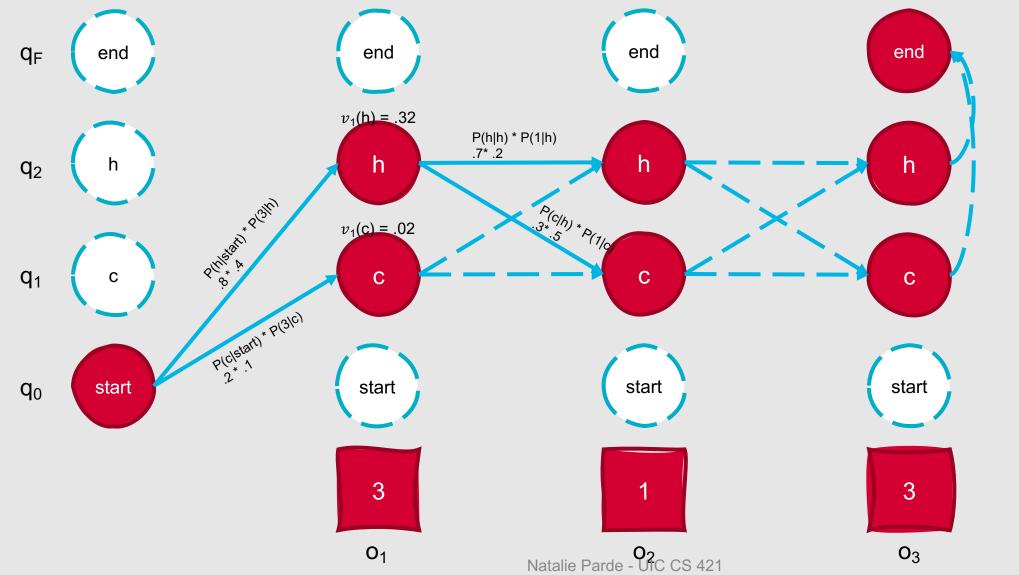


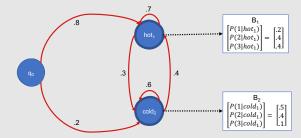


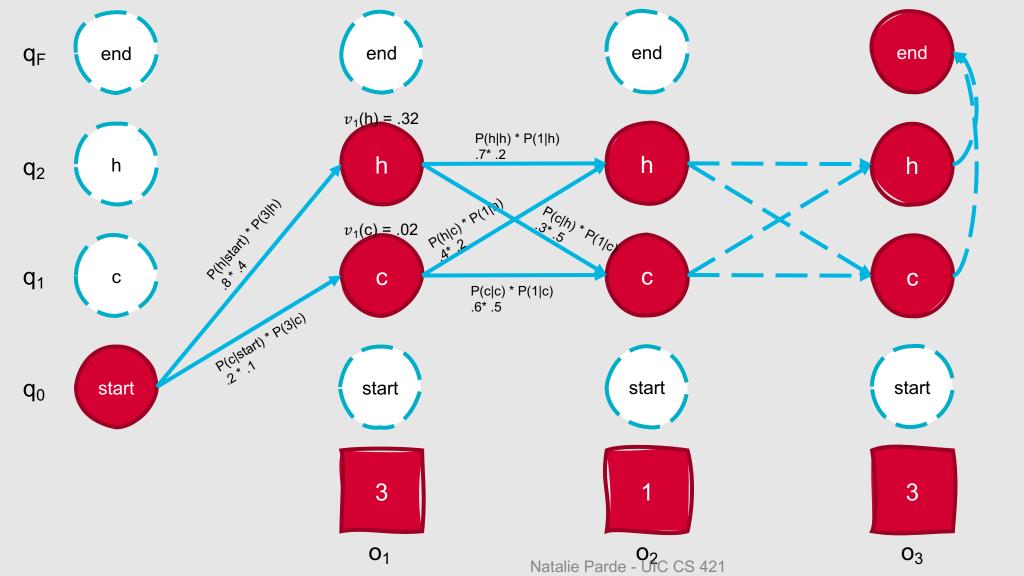


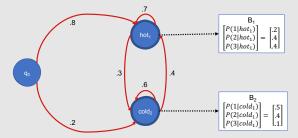


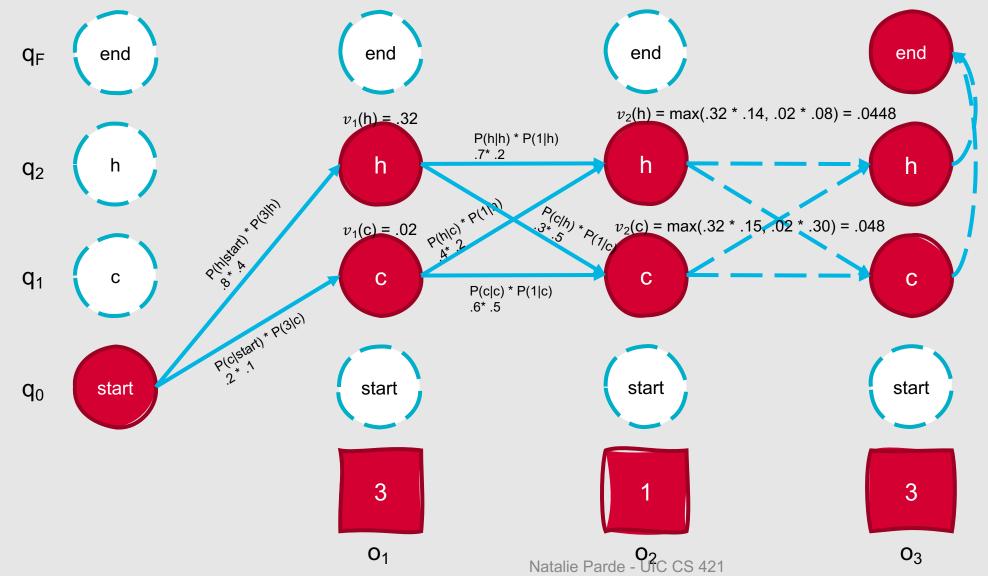


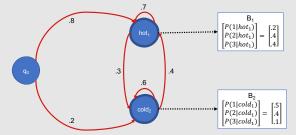


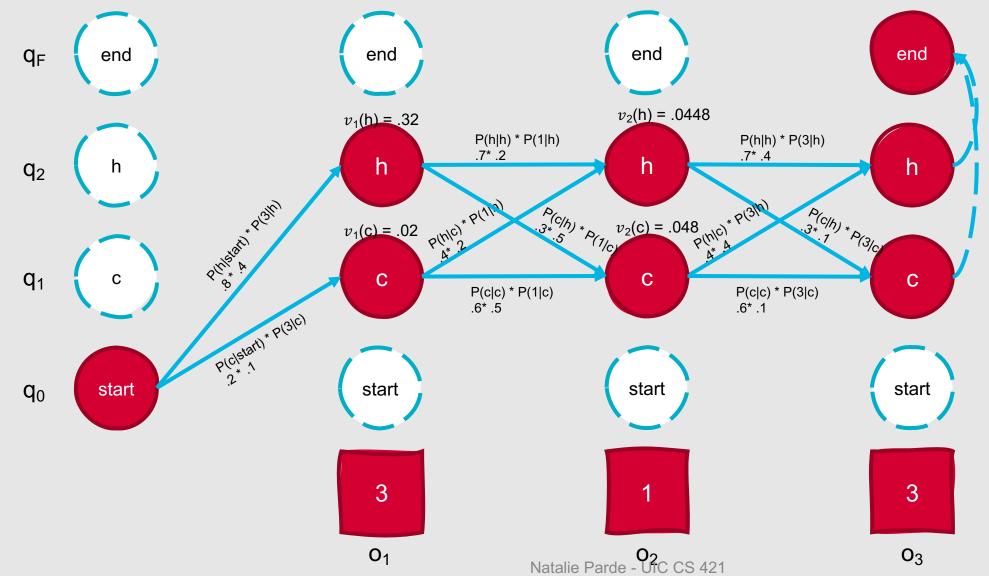


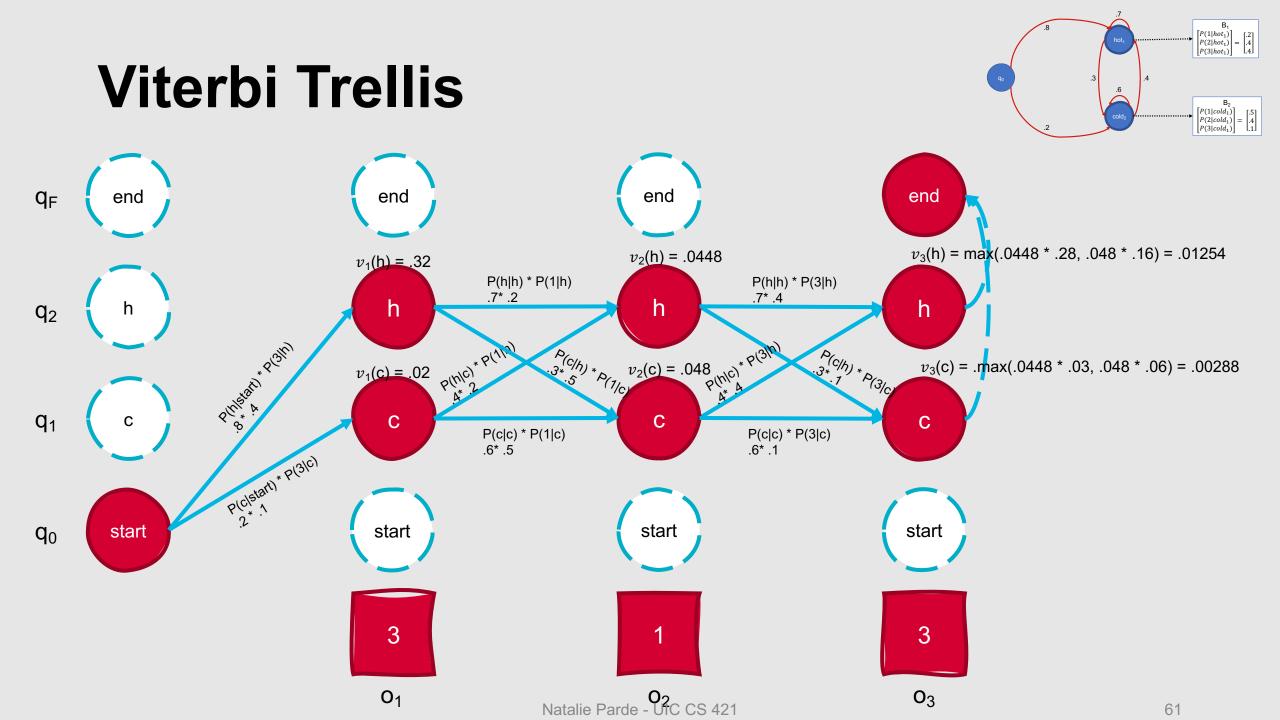


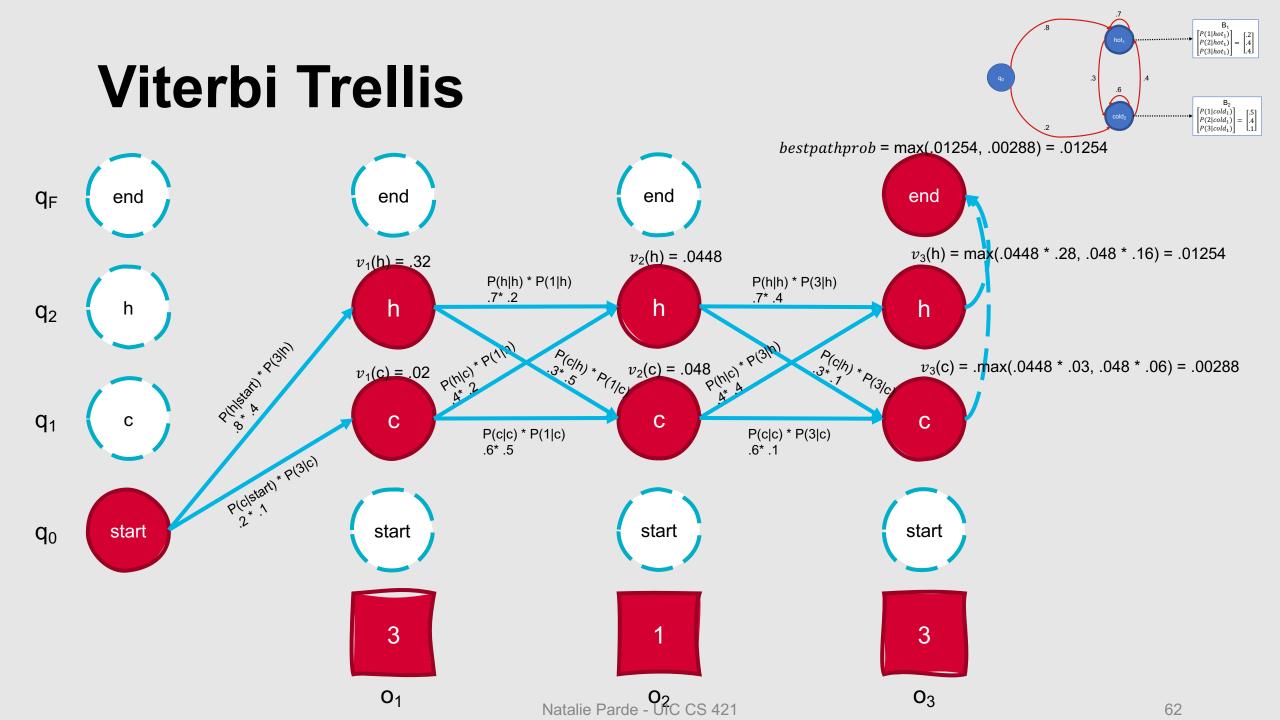


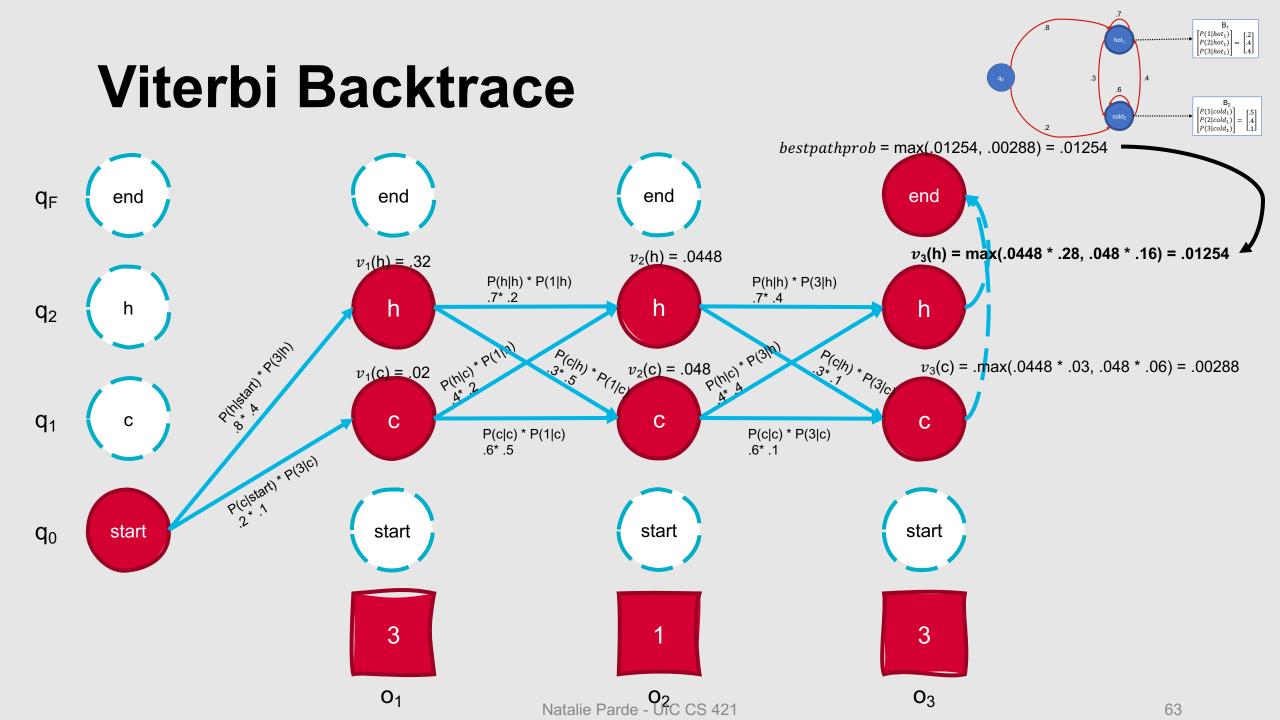


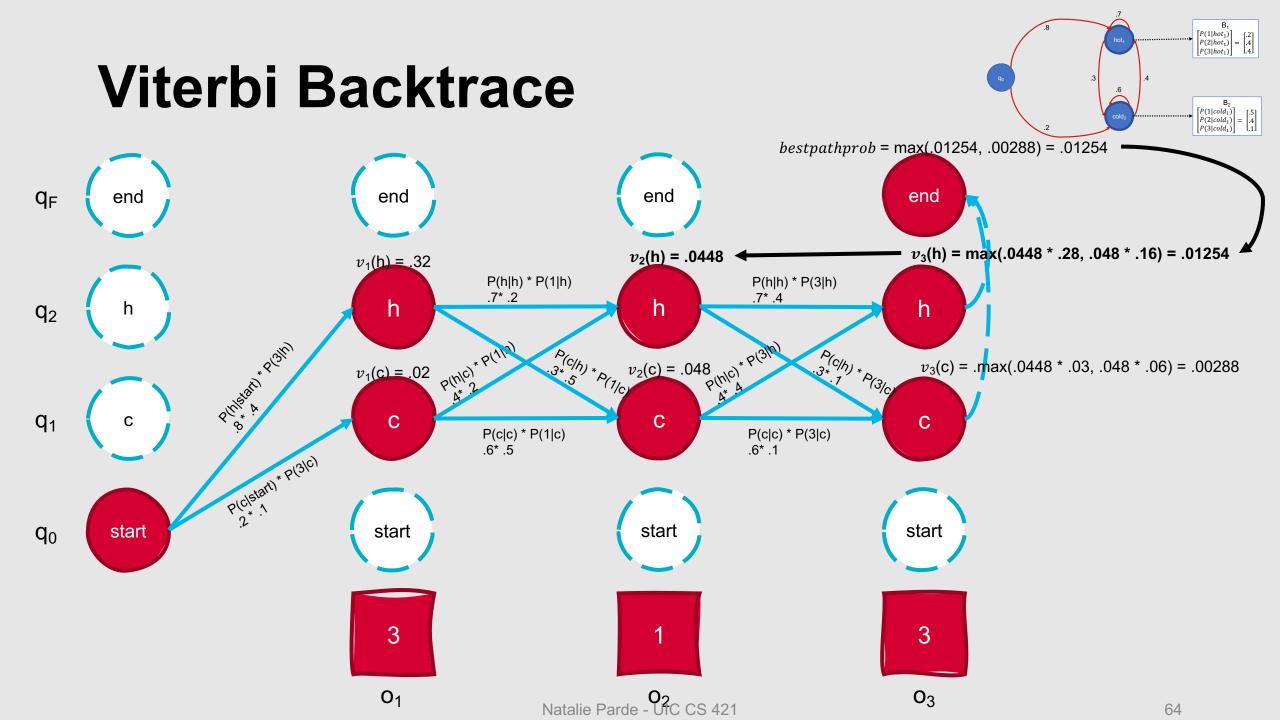


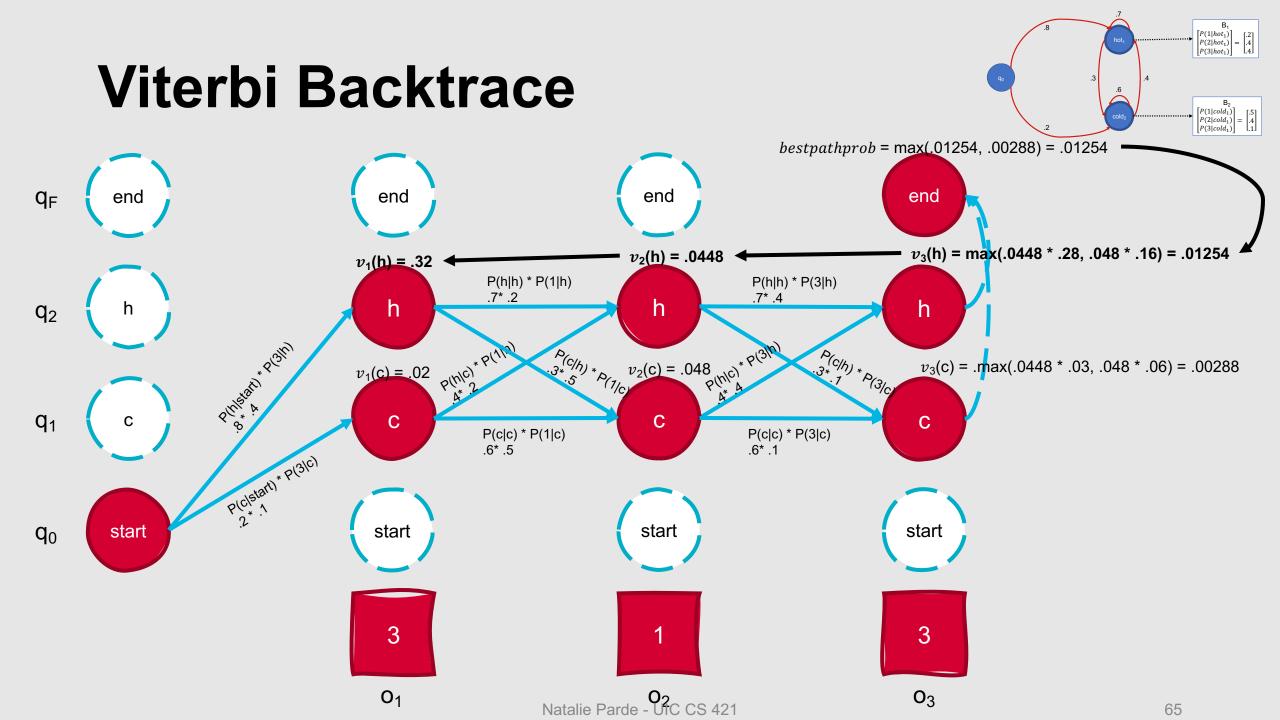


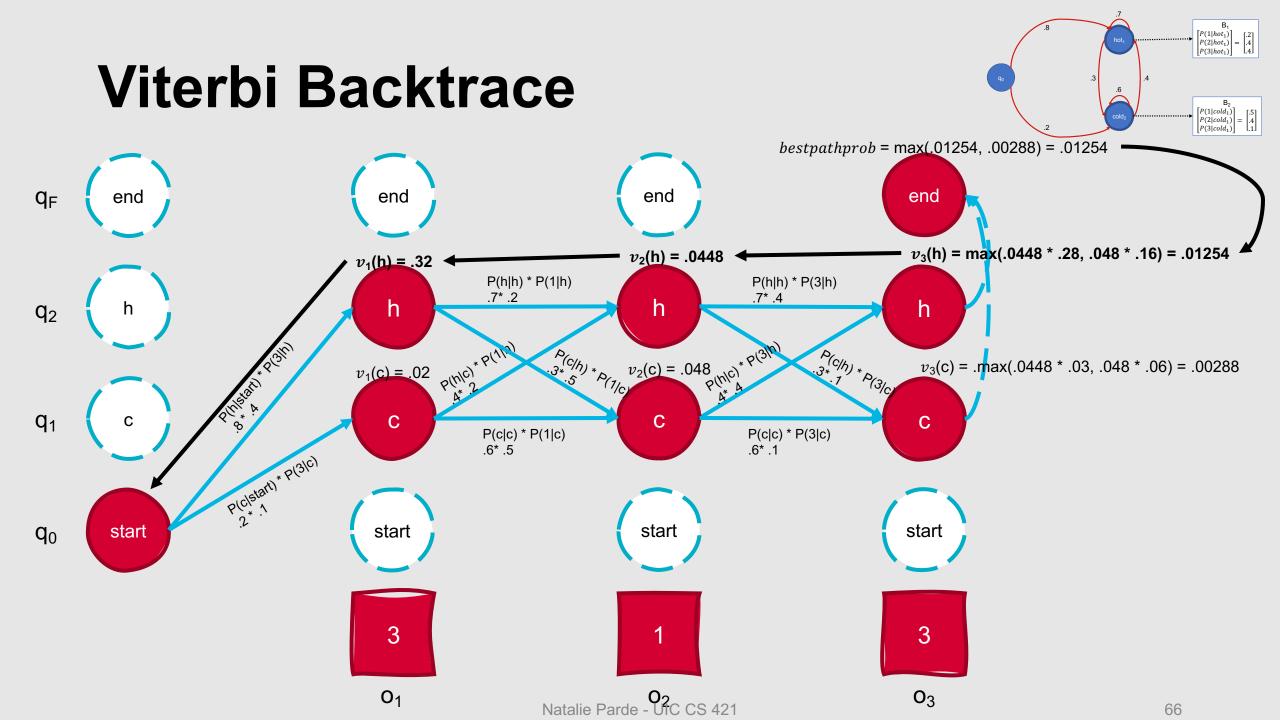






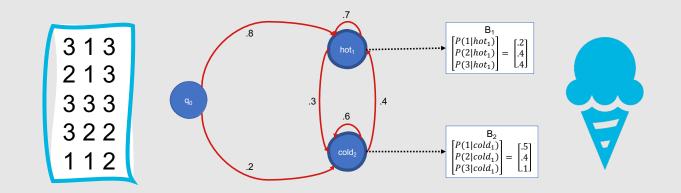






Finally ... learning!

• If we have a set of observations, can we learn the parameters (transition probabilities and observation likelihoods) directly?





Forward-Backward Algorithm

- Special case of expectation-maximization (EM) algorithm
- Also known as the Baum-Welch algorithm
- Input:
 - Unlabeled sequence of observations, O
 - Vocabulary of hidden states, Q
- Output: Transition probabilities and observation likelihoods

••••

How does the algorithm compute these outputs?

- Iteratively estimate the counts for transitions from one state to another
 - Start with base estimates for a_{ij} and b_j, and iteratively improve those estimates
- Get estimated probabilities by:
 - Computing the forward probability for an observation
 - Dividing that probability mass among all the different paths that contributed to this forward probability

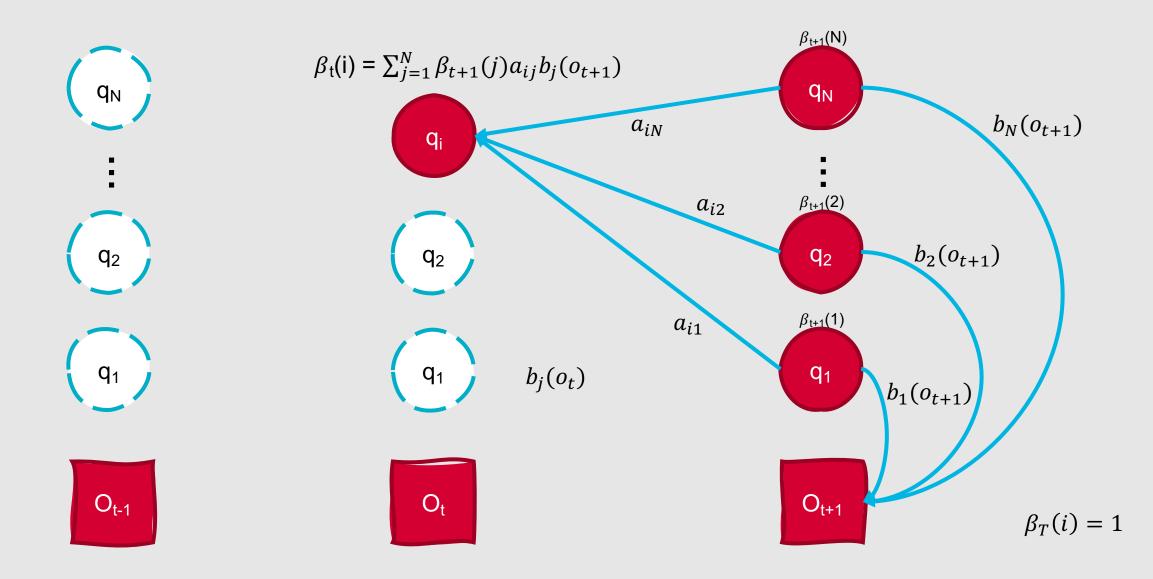
The second part of this process uses the backward algorithm.

• We define the backward probability as follows:

•
$$\beta_t(i) = P(o_{t+1}, o_{t+2}, ..., o_T | q_t = i, \lambda)$$

- This is the probability of generating partial observations from time t+1 until the end of the sequence, given that the HMM λ is in state *i* at time *t*
- Also computed using a trellis, but moves backwards instead

Backward Step



Once we compute backward probabilities, we can start estimating transition probabilities and observation likelihoods.

• We re-estimate transition probabilities, a_{ii} , as follows:

•
$$\widehat{a_{ij}} = \frac{\text{expected \# transitions from state } i \text{ to state } j}{\text{expected \# transitions from state } i} = \frac{\sum_{t=1}^{T-1} \frac{a_t(t)a_{aij}b_j\beta_{t+1}(j)}{a_T(q_F)}}{\sum_{t=1}^{T-1} \sum_{i=1}^{N} \frac{a_t(i)a_{aij}b_j\beta_{t+1}(j)}{a_T(q_F)}}$$

• Check out the course textbook (Appendix A) for an in-depth discussion of how the numerator and denominator above are derived!

 It's common to simplify the inner portion of the summation in the equation above:

•
$$\zeta_t(i,j) = \frac{a_t(i)a_{aij}b_j\beta_{t+1}(j)}{a_T(q_F)}$$

• Therefore:

•
$$\widehat{a_{ij}} = \frac{\sum_{t=1}^{T-1} \xi_t(i,j)}{\sum_{t=1}^{T-1} \sum_{j=1}^{N} \xi_t(i,j)}$$

Re-Estimating Observation Likelihood

- We re-estimate *b_i* as follows:
 - $\hat{b}_j(v_k) = \frac{\text{expected \# of times in state } j \text{ and observing symbol } v_k}{\text{expected number of times in state } j} = \frac{\sum_{t=1}^T \text{s.t. } o_t = v_k}{\sum_{t=1}^T \frac{a_t(j)\beta_t(j)}{a_T(q_F)}}$
- Again, to simplify presentation we can abstract away the inner portion of the summation:
 - $\gamma_t(j) = \frac{a_t(j)\beta_t(j)}{a_T(q_F)}$
- Therefore:

•
$$\widehat{b}_{j}(v_{k}) = \frac{\sum_{t=1}^{T} \text{s.t. } o_{t} = v_{k}}{\sum_{t=1}^{T} \gamma_{t}(j)}$$

Forward-Backward Algorithm

initialize A and B
iterate until convergence:

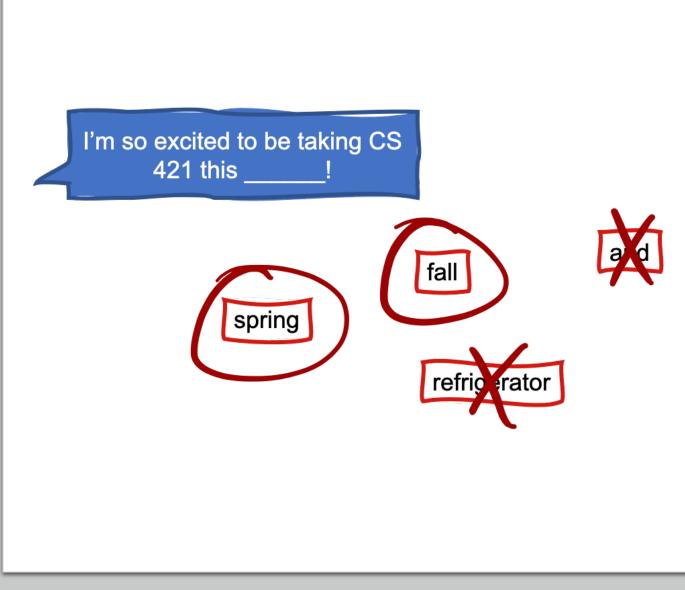
Expectation Step compute $\gamma_t(j)$ for all t and j compute $\zeta_t(i,j)$ for all t, i, and j

Maximization Step $\alpha_{ij} = \widehat{a_{ij}}$ for all i and j $b_j(v_k) = \widehat{b_j}(v_k)$ for all j, and all v_k in the output vocab V Summary: Hidden Markov Models

- HMMs are probabilistic generative models for sequences
- They make predictions based on underlying hidden states
- Three fundamental HMM problems include:
 - Computing the likelihood of a sequence of observations
 - Determining the best sequence of hidden states for an observed sequence
 - Learning HMM parameters given an observation sequence and a set of hidden states
- Observation likelihood can be computed using the forward algorithm
- Sequences of hidden states can be decoded using the Viterbi algorithm
- HMM parameters can be learned using the forwardbackward algorithm

Language Modeling

• The process of building models that predict the likelihood of word or character sequences in a language



• • • • • • • • • • •

Why is language modeling useful?

- Helps identify words in noisy, ambiguous input
 - Speech recognition or autocorrect
- Helps generate natural-sounding language
 - Machine translation or image captioning

Language models come in many forms!

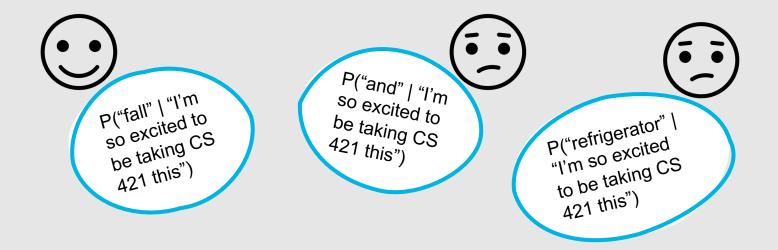
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- Less complex:
 - N-gram language models
- More sophisticated
 - Neural language models

N-Gram Language Models

- Goal: Predict P(word|history)
 - P("spring" | "I'm so excited to be taking CS 421 this")



How do we predict these probabilities?

- One method: Estimate it from frequency counts
 - Take a large corpus
 - Count the number of times you see the history
 - Count the number of times the specified word follows the history

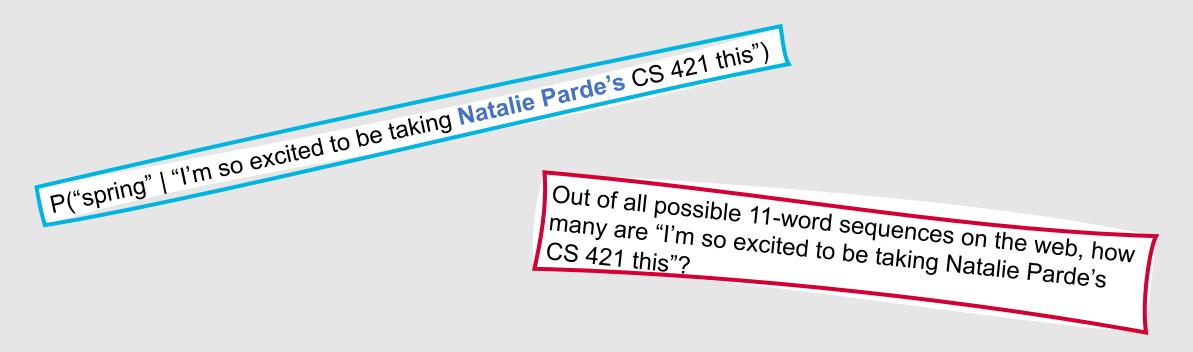
P("spring" | "I'm so excited to be taking CS 421 this") = C("I'm so excited to be taking CS 421 this spring") / C("I'm so excited to be taking CS 421 this")





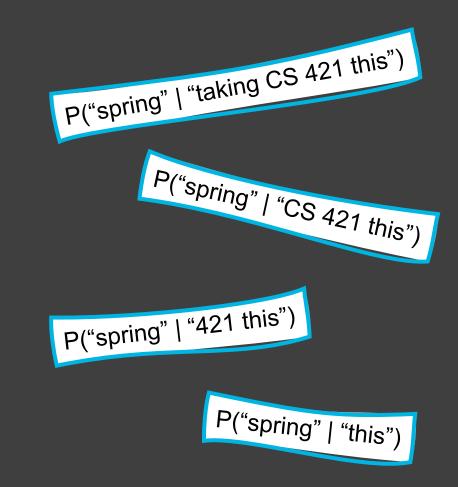
However, we don't necessarily want to use our *entire* history.

- What if our history contains uncommon words?
- What if we have limited computing resources?



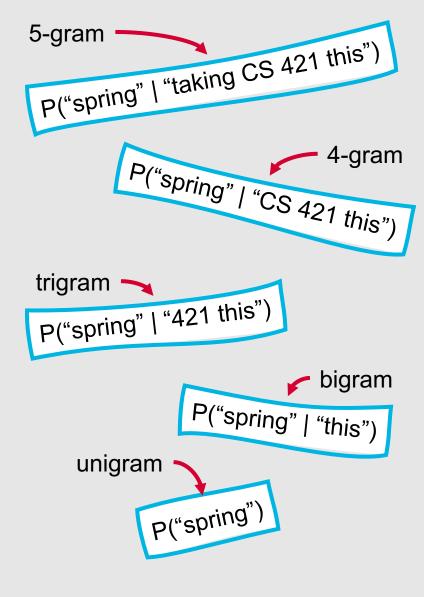
We need a better way to estimate P(word|history)!

- The solution: Instead of computing the probability of a word given its entire history, approximate the history using the most recent few words.
- We do this using fixed-length **n-grams**.



Special N-Grams

- Most higher-order (n>3) ngrams are simply referred to using the value of n
 - 4-gram
 - 5-gram
- However, lower-order ngrams are often referred to using special terms:
 - Unigram (1-gram)
 - Bigram (2-gram)
 - Trigram (3-gram)



N-gram models follow the Markov assumption.

- We can predict the probability of some future unit without looking too far into the past
 - **Bigram language model:** Probability of a word depends only on the previous word
 - Trigram language model: Probability of a word depends only on the two previous words
 - N-gram language model: Probability of a word depends only on the *n*-1 previous words

More formally....

- $P(w_n | w_1^{n-1}) \approx P(w_n | w_{n-N+1}^{n-1})$
- We can then multiply these individual word probabilities together to get the probability of a word sequence
 - $P(w_1^n) \approx \prod_{k=1}^n P(w_k | w_{k-N+1}^{k-1})$

P("Summer break	k is already over?")	
	P("over?" "already") * P("already" "is") * P("is" "break") * P("break" "Summer")	
	P("is" "break") * P("break" "Summer")	

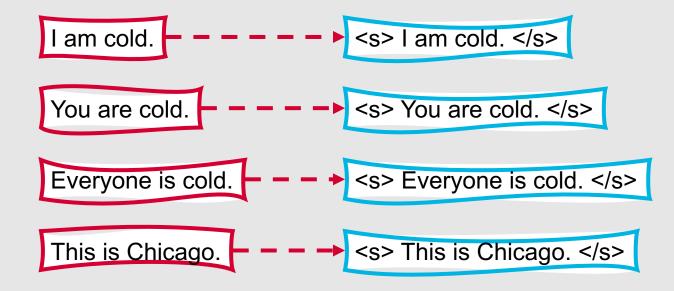
To compute ngram probabilities, maximum likelihood estimation is often used.

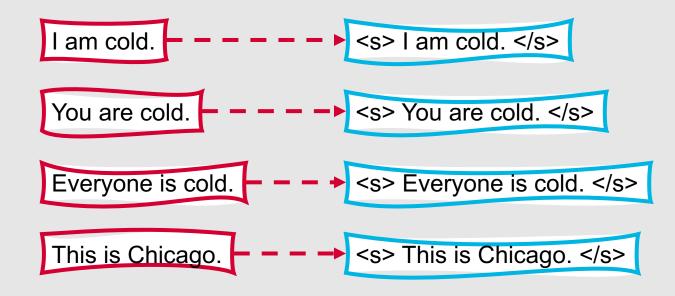
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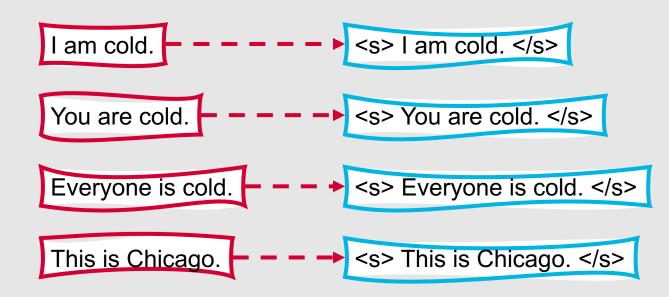
- Maximum Likelihood Estimation (MLE):
 - Get the requisite n-gram frequency counts from a corpus
 - Normalize them to a 0-1 range
 - P(w_n | w_{n-1}) = # of occurrences of the bigram w_{n-1} w_n / # of occurrences of the unigram w_{n-1}





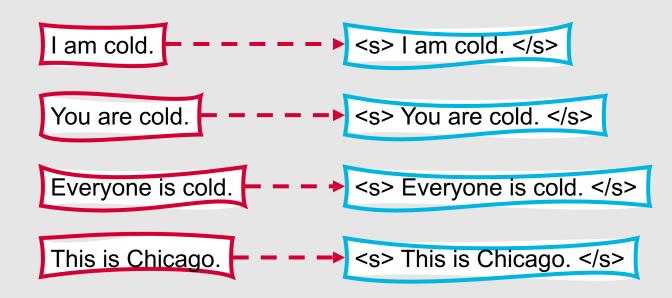


Bigram	Frequency
<s> </s>	1
l am	1
am cold.	1
cold.	3
is Chicago.	1
Chicago.	1



Bigram	Freq.
<s> </s>	1
lam	1
am cold.	1
cold.	3
is Chicago.	1
Chicago.	1

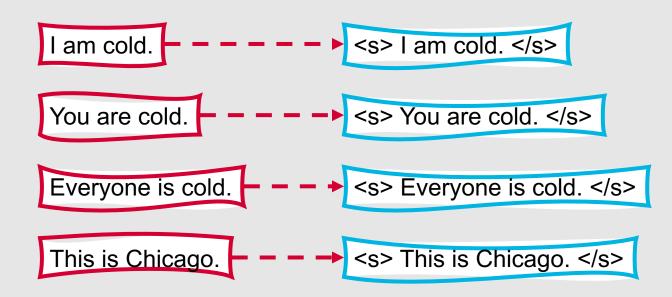
Unigram	Freq.
<s></s>	4
I	1
am	1
cold.	3
Chicago.	1
	4



Bigram	Freq.
<s> </s>	1
lam	1
am cold.	1
cold.	3
is Chicago.	1
Chicago.	1

Unigram	Freq.
<s></s>	4
I	1
am	1
cold.	3
Chicago.	1
	4

P("I" | "<s>") = C("<s>I") / C("<s>") = 1 / 4 = 0.25

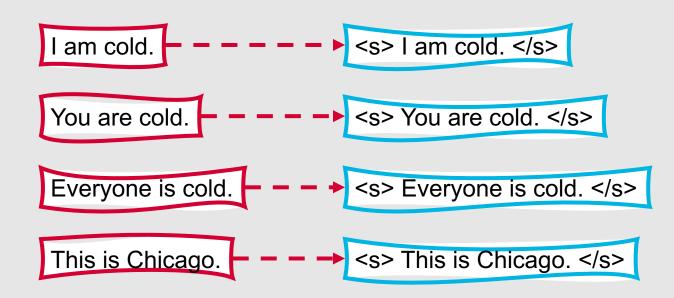


Bigram	Freq.
<s> </s>	1
lam	1
am cold.	1
cold.	3
is Chicago.	1
Chicago.	1

Unigram	Freq.
<5>	4
I	1
am	1
cold.	3
Chicago.	1
	4

P("I" | "<s>") = C("<s>I") / C("<s>") = 1 / 4 = 0.25

P((</s>) | (cold.)) = C((cold. </s>) / C((cold.)) = 3 / 3 = 1.00



Bigram	Freq.
<s> </s>	1
l am	1
am cold.	1
cold.	3
is Chicago.	1
Chicago.	1

Unigram	Freq.
<5>	4
I	1
am	1
cold.	3
Chicago.	1
	4

$$P("I" | "~~") = C("~~I") / C("~~") = 1 / 4 = 0.25~~~~~~$$
$$P("" | "cold.") = C("cold. ") / C("cold.") = 3 / 3 = 1.00$$

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We can learn a lot of useful things from n-gram statistics!

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- Syntactic information
 - Do nouns often follow verbs?
 - Do verbs usually follow specific unigrams?
- Task-relevant information
 - Is it likely that virtual assistants will hear the word "I" in a user's input?
- Cultural or sociological information
 - Are people likelier to want quesadillas than haggis?

Which type of ngram is best?

- In general, the highest-order value of *n* that your data can support
- Sparsity increases with order, and sparse feature vectors are not very useful when training statistical models
- Make sure that your dataset is large enough to handle your selected n-gram size



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We've learned how to build ngram language models, but how do we evaluate them?

- Two types of evaluation paradigms:
 - Extrinsic
 - Intrinsic
- Extrinsic evaluation: Embed the language model in an application, and compute changes in task performance
- Intrinsic evaluation: Measure the quality of the model, independent of any application

Perplexity

- Intrinsic evaluation metric for language models
- Perplexity (PP) of a language model on a test set is the inverse probability of the test set, normalized by the number of words in the test set



More formally....



•
$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2...w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1...w_{i-1})}}$$

- Where *W* is a test set containing words *w*₁, *w*₂, ..., *w*_n
- History size depends on n-gram size
 - $P(w_i|w_{i-1})$ vs $P(w_i|w_{i-2}w_{i-1})$, etc.
- Higher conditional probability of a word sequence \rightarrow lower perplexity
 - Minimizing perplexity = maximizing test set probability according to the language model

Training Set

Word	Frequency
CS	10
421	10
Statistical	10
Natural	10
Language	10
Processing	10
University	10
of	10
Illinois	10
Chicago	10



Word	Frequency
CS	10
421	10
Statistical	10
Natural	10
Language	10
Processing	10
University	10
of	10
Illinois	10
Chicago	10

Test String

CS 421 Statistical Natural Language Processing University of Illinois Chicago



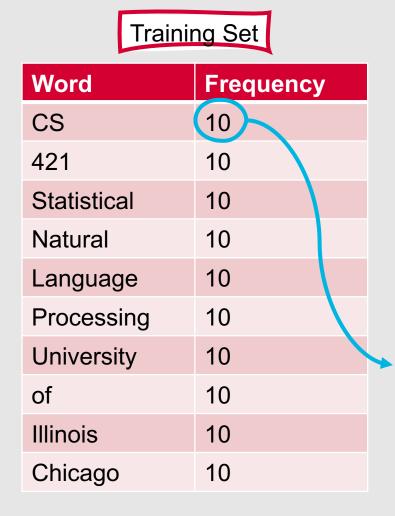
Word	Frequency
CS	10
421	10
Statistical	10
Natural	10
Language	10
Processing	10
University	10
of	10
Illinois	10
Chicago	10

Test String

CS 421 Statistical Natural Language Processing University of Illinois Chicago

$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$

P

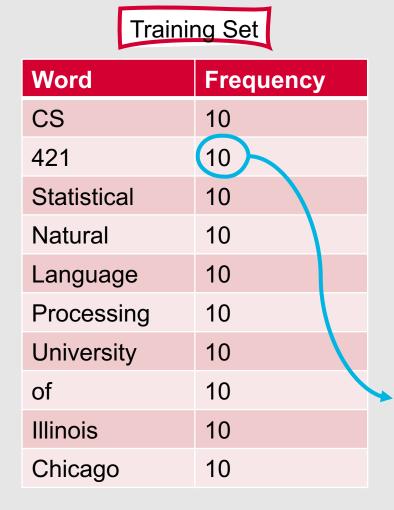


Test String

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$$P(W) = \sqrt[n]{\frac{1}{P(w_1 w_2 \dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i | w_1 \dots w_{i-1})}}$$

P("CS") = C("CS") / C(<all unigrams>) = 10/100 = 0.1



Test String

CS 421 Statistical Natural Language Processing University of Illinois Chicago

$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$

P("CS") = C("CS") / C(<all unigrams>) = 10/100 = 0.1 P("421") = C("421") / C(<all unigrams>) = 10/100 = 0.1



Word	Frequency	P(Word)
CS	10	0.1
421	10	0.1
Statistical	10	0.1
Natural	10	0.1
Language	10	0.1
Processing	10	0.1
University	10	0.1
of	10	0.1
Illinois	10	0.1
Chicago	10	0.1

Test String

CS 421 Statistical Natural Language Processing University of Illinois Chicago

$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$



Word	Frequency	P(Word)
CS	10	0.1
421	10	0.1
Statistical	10	0.1
Natural	10	0.1
Language	10	0.1
Processing	10	0.1
University	10	0.1
of	10	0.1
Illinois	10	0.1
Chicago	10	0.1

Test String

CS 421 Statistical Natural Language Processing University of Illinois Chicago

$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$

PP("CS 421 Statistical Natural Language Processing University of Illinois Chicago")



Word	Frequency	P(Word)
CS	1	
421	1	
Statistical	1	
Natural	1	
Language	1	
Processing	1	
University	1	
of	1	
Illinois	1	
Chicago	91	

Test String

Illinois Chicago Chicago Chicago Chicago Chicago Chicago Chicago Chicago

$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$



Word	Frequency	P(Word)
CS	1	0.01
421	1	0.01
Statistical	1	0.01
Natural	1	0.01
Language	1	0.01
Processing	1	0.01
University	1	0.01
of	1	0.01
Illinois	1	0.01
Chicago	91	0.91

Test String

Illinois Chicago Chicago Chicago Chicago Chicago Chicago Chicago Chicago

$$PP(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$



Word	Frequency	P(Word)
CS	1	0.01
421	1	0.01
Statistical	1	0.01
Natural	1	0.01
Language	1	0.01
Processing	1	0.01
University	1	0.01
of	1	0.01
Illinois	1	0.01
Chicago	91	0.91

Test String

Illinois Chicago Chicago

$$P(W) = \sqrt[n]{\frac{1}{P(w_1w_2\dots w_n)}} = \sqrt[n]{\prod_{i=1}^n \frac{1}{P(w_i|w_1\dots w_{i-1})}}$$

PP("CS 521 Statistical Natural Language Processing University of Illinois Chicago")



Perplexity can be used to compare different language models.

Which language model is best?

- Model A: Perplexity = 962
- Model B: Perplexity = 170
- Model C: Perplexity = 109



Perplexity can be used to compare different language models.

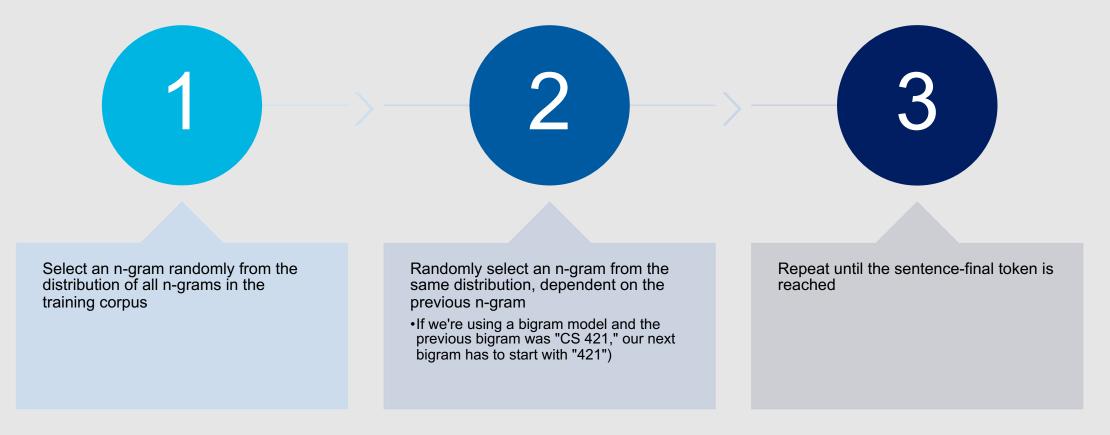
Which language model is best?

- Model A: Perplexity = 962
- Model B: Perplexity = 170
 Model C: Perplexity = 109

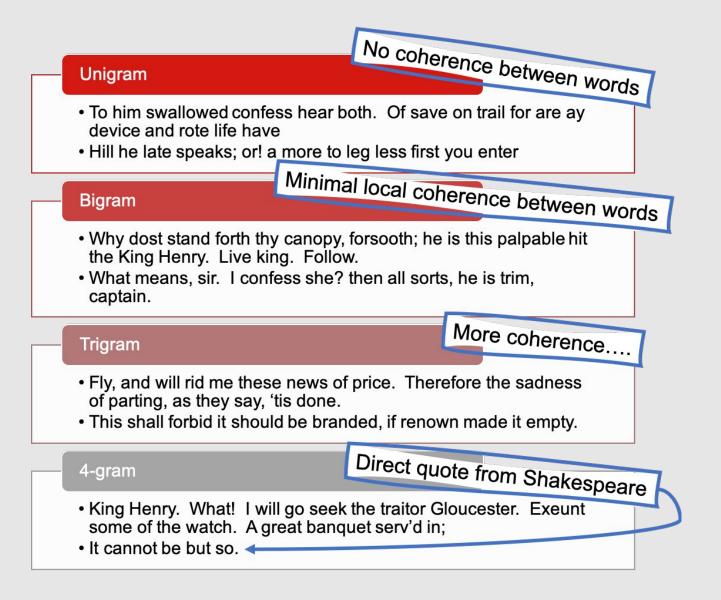
A cautionary note....

- Improvements in perplexity do not guarantee improvements in task performance!
- However, the two are often correlated (and perplexity is quicker and easier to check)
- Strong language model evaluations also include an extrinsic evaluation component

Just like with HMMs, we can use n-gram language models to generate text.



N-gram order affects generation output!



In the case of a Shakespearean language model....

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- Recall that the corpus of all Shakespearean text is relatively small (by modern NLP standards)
 - 29,066 vocabulary words
 - 884,647 tokens
- This means higher-order n-gram matrices are sparse!
 - Only five possible continuations for "It cannot be but" ("that," "I," "he," "thou," and "so") ...probability for all other continuations is assumed to be zero

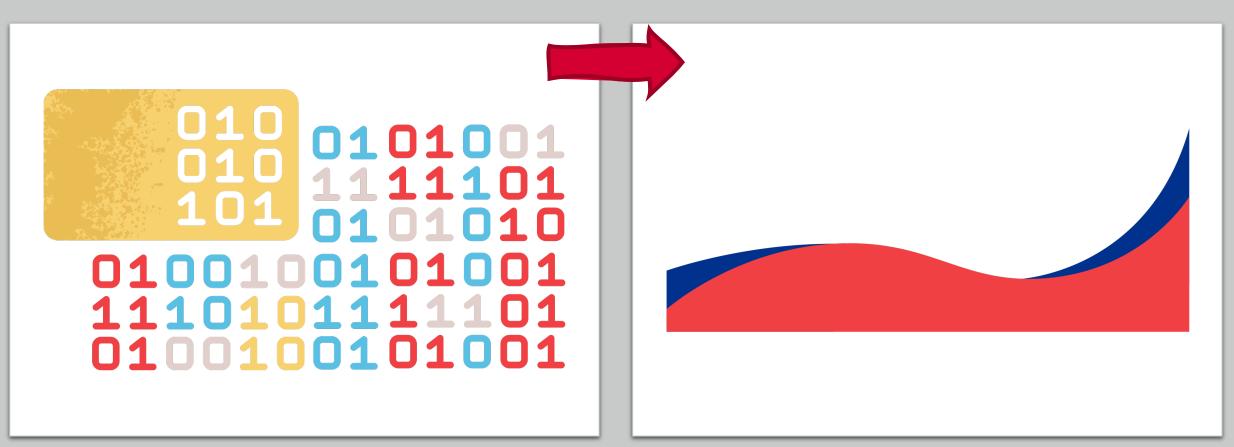
"Zero" probabilities create challenges for language models.

- In practice, language is varied and often unexpected---few combinations are truly impossible
- Zero probabilities also interfere with perplexity calculations
- Zero probabilities occur in two different scenarios:
 - Unknown words (out-ofvocabulary words)
 - Known words in unseen contexts

Modeling Unknown Words

- Add a pseudoword <UNK> to the vocabulary
- Then....
 - Option A:
 - Choose a fixed words list
 - Convert any words not in that list to <UNK>
 - Estimate the probabilities for <UNK> like any other word
 - Option B:
 - Replace all words occurring fewer than n times with <UNK>
 - Estimate the probabilities for <UNK> like any other word
 - Option C:
 - Replace the first occurrence of each word with <UNK>
 - Estimate the probabilities for <UNK> like any other word
- Beware: If <UNK> ends up with a high probability (e.g., because you have a small vocabulary), your language model will have artificially lower perplexity!
 - Make sure to compare to other language models using the same vocabulary to avoid gaming this metric

We can handle known words in previously unseen contexts by applying smoothing techniques.



Smoothing

- Taking a bit of the probability mass from more frequent events and giving it to unseen events.
 - · Sometimes also called "discounting"
- Many different smoothing techniques:
 - Laplace (add-one)
 - Add-k
 - Stupid backoff
 - Kneser-Ney

Bigram	Frequency
CS 421	8
CS 590	5
CS 594	2
CS 521	0 😢

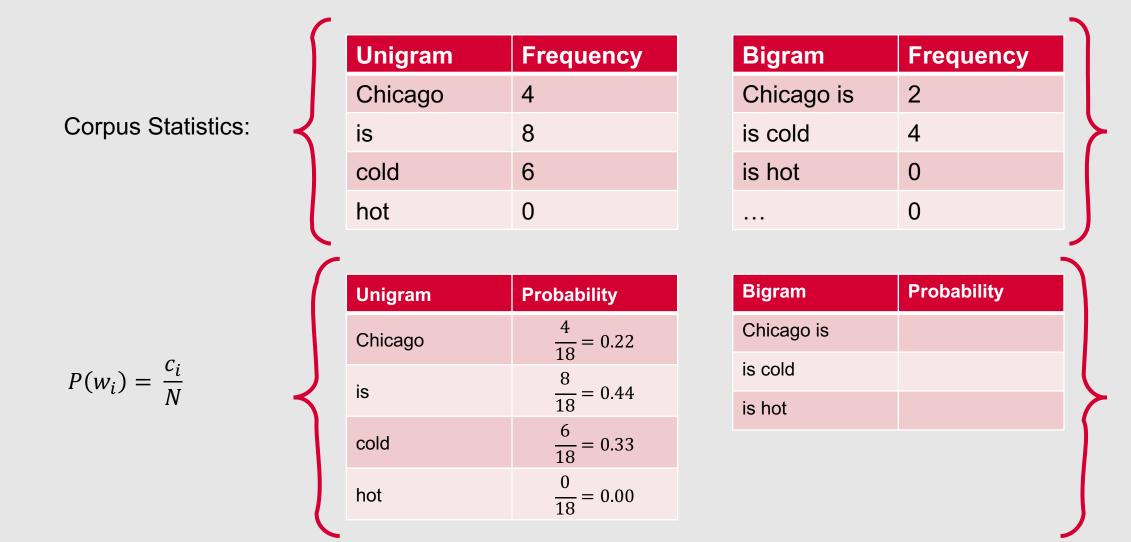
Bigram	Frequency
CS 421	7
CS 590	5
CS 594	2
CS 521	1 🖊 🕰

Laplace Smoothing

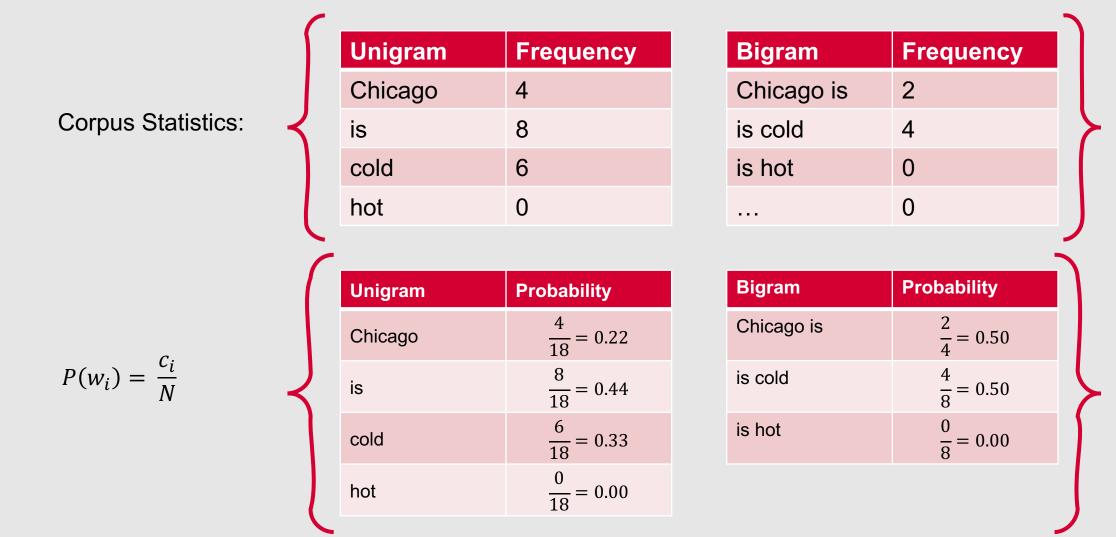
- Add one to all n-gram counts before they are normalized into probabilities
- Not the highest-performing technique for language modeling, but a useful baseline
 - Practical method for other text classification tasks

•
$$P(w_i) = \frac{c_i}{N} \rightarrow P_{\text{Laplace}}(w_i) = \frac{c_i+1}{N+V}$$

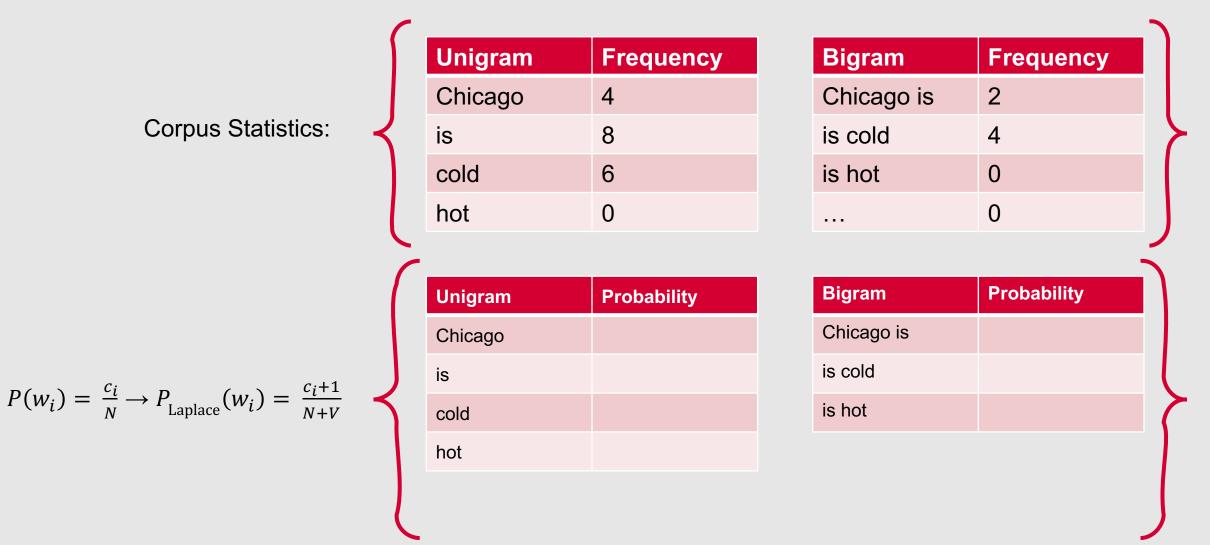
	5	Unigram	Frequency	Bigram	Frequency	IJ
		Chicago	4	Chicago is	2	
Corpus Statistics:	$\boldsymbol{\prec}$	is	8	is cold	4	\
		cold	6	is hot	0	
		hot	0		0	
)

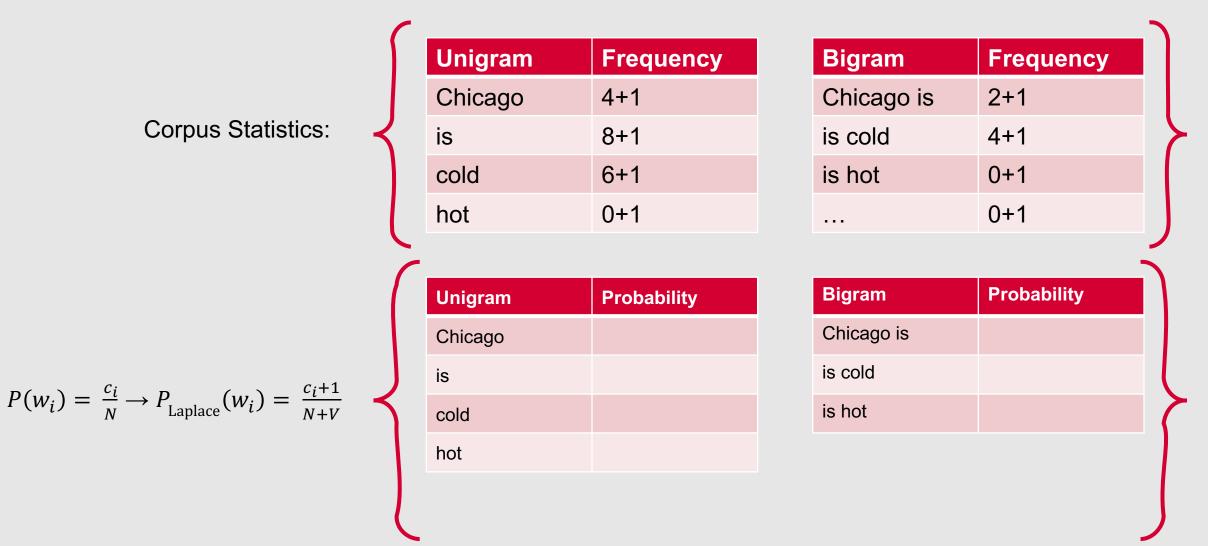


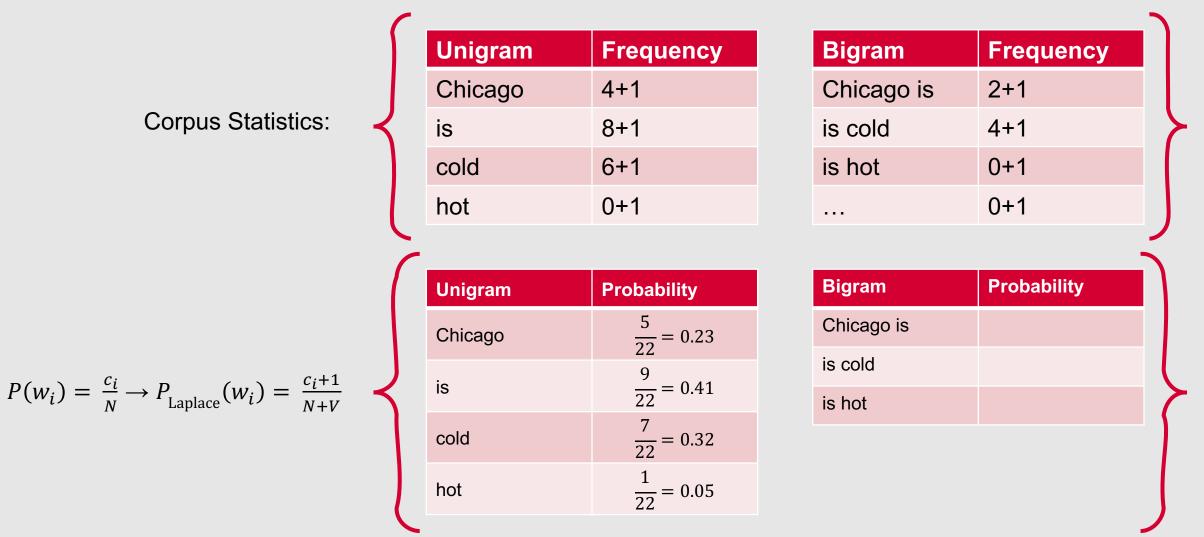
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		-				
			Unigram	Frequency	Bigram	Frequency
			Chicago	4	Chicago is	2+1
Corpu	s Statistics:	\prec	is	8	is cold	4+1
Bigram	Frequency		cold	6	is hot	0+1
Chicago Chicago	0+1		hot	0		0+1
Chicago is	2+1					
Chicago cold	0+1		Unigram	Probability	Bigram	Probability
Chicago hot	0+1		Chicago	$\frac{5}{22} = 0.23$	Chicago is	$\frac{3}{4+4} = \frac{3}{8} = 0.38$
$P(w_i) = \frac{c_i}{N} \rightarrow P_{\text{Laplace}}$	$_{ce}(w_i) = \frac{c_i + 1}{N + V}$	$\left\{ \right.$	is	$\frac{9}{22} = 0.41$	is cold	$\frac{5}{8+4} = \frac{5}{12} = 0.42$

cold

hot

$$P(w_i) = \frac{c_i}{N} \rightarrow P_{\text{Laplace}}(w_i) = \frac{c_i+1}{N+V}$$

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 $\frac{7}{22} = 0.32$

 $\frac{1}{22} = 0.05$

is hot

 $\frac{1}{8+4} = \frac{1}{12} = 0.08$

Probabilities: Before and After

Bigram	Probability
Chicago is	$\frac{2}{4} = 0.50$
is cold	$\frac{4}{8} = 0.50$
is hot	$\frac{0}{8} = 0.00$
Bigram	Probability
Chicago is	$\frac{3}{8} = 0.38$
is cold	$\frac{5}{12} = 0.42$
is hot	$\frac{1}{12} = 0.08$

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Add-K Smoothing

- Moves a bit less of the probability mass from seen to unseen events
- Rather than adding one to each count, add a fractional count
 - 0.5
 - 0.05
 - 0.01
- The value *k* can be optimized on a validation set

•
$$P(w_i) = \frac{c_i}{N} \to P_{Add-K}(w_i) = \frac{c_i + k}{N + kV}$$

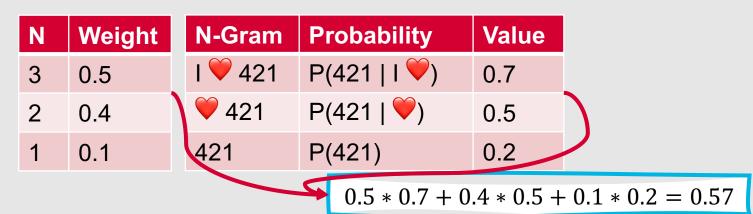
• $P(w_n | w_{n-1}) = \frac{c(w_{n-1}w_n)}{c(w_{n-1})} \to P_{Add-K}(w_n | w_{n-1}) = \frac{c(w_{n-1}w_n) + kV}{c(w_{n-1}) + kV}$

Add-K smoothing is useful for some tasks, but still tends to be suboptimal for language modeling.

- Other smoothing techniques?
 - Backoff: Use the specified n-gram size to estimate probability if its count is greater than 0; otherwise, *backoff* to a lower-order n-gram
 - Interpolation: Mix the probability estimates from multiple n-gram sizes, weighing and combining the n-gram counts



Interpolation



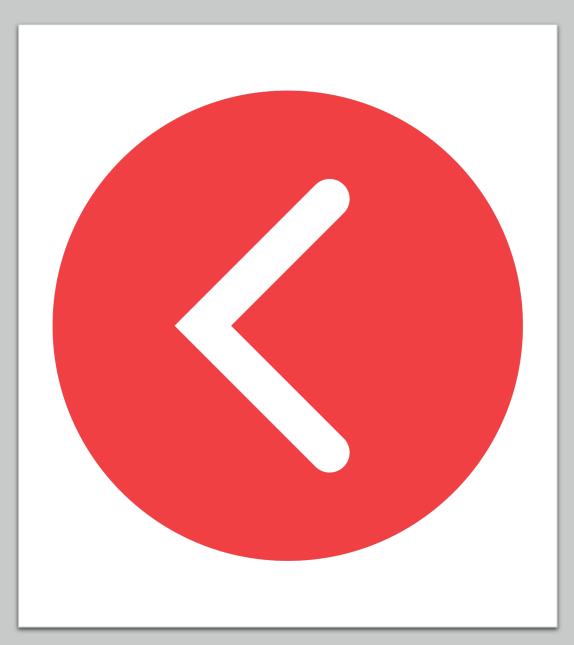
- Linear interpolation
 - $P'(w_n|w_{n-2}w_{n-1}) = \lambda_1 P(w_n|w_{n-2}w_{n-1}) + \lambda_2 P(w_n|w_{n-1}) + \lambda_3 P(w_n)$ • Where $\sum_i \lambda_i = 1$
- Conditional interpolation
 - $P'(w_n|w_{n-2}w_{n-1}) = \lambda_1(w_{n-2}^{n-1})P(w_n|w_{n-2}w_{n-1}) + \lambda_2(w_{n-2}^{n-1})P(w_n|w_{n-1}) + \lambda_3(w_{n-2}^{n-1})P(w_n)$

N-Gram	Probability	Value	Weight
I 💜 421	P(421 I 💛)	0.7	0.5
l 希 421	P(421 I 稀)	0.7	0.1

Context-conditioned weights

Backoff

- If the n-gram we need has zero counts, approximate it by backing off to the (n-1)-gram
- Continue backing off until we reach a size that has non-zero counts
- Just like with smoothing, some probability mass from higher-order n-grams needs to be redistributed to lower-order n-grams



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Katz Backoff

- Incorporate a function α to distribute probability mass to lower-order n-grams
- Rely on a discounted probability P* if the n-gram has non-zero counts
- Otherwise, recursively back off to the Katz probability for the (n-1)-gram

•
$$P_{BO}(w_n | w_{n-N+1}^{n-1}) = \begin{cases} P^*(w_n | w_{n-N+1}^{n-1}), & \text{if } c(w_{n-N+1}^n) > 0\\ \alpha(w_{n-N+1}^{n-1}) P_{BO}(w_n | w_{n-N+2}^{n-1}), & \text{otherwise} \end{cases}$$

- One of the most commonly used and best-performing n-gram smoothing methods
- Incorporates absolute discounting

$$P_{\text{AbsoluteDiscounting}}(w_i|w_{i-1}) = \frac{C(w_{i-1}w_i)-d}{\sum_{\nu} C(w_{i-1}\nu)} + \lambda(w_{i-1})P(w_i)$$

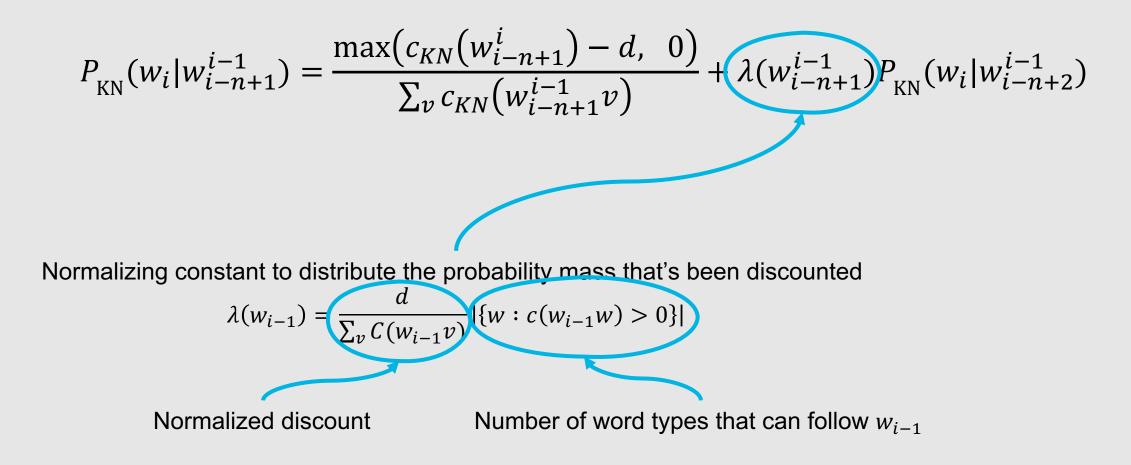
Discounted Bigram Unigram with interpolation weight

- Objective: Capture the intuition that although some lower-order n-grams are frequent, they are mainly only frequent in specific contexts
 - tall nonfat decaf peppermint
 - "york" is a more frequent unigram than "mocha" (7.4 billion results vs. 135 million results on Google), but it's mainly frequent when it follows the word "new"
- Creates a unigram model that estimates the probability of seeing the word w as a novel continuation, in a new unseen context
 - Based on the number of different contexts in which *w* has already appeared

•
$$P_{\text{Continuation}}(w) = \frac{|\{v:C(vw)>0\}|}{|\{(u',w'):C(u'w')>0\}|}$$

$$P_{\rm KN}(w_i|w_{i-n+1}^{i-1}) = \frac{\max(c_{\rm KN}(w_{i-n+1}^i) - d, 0)}{\sum_{\nu} c_{\rm KN}(w_{i-n+1}^{i-1}\nu)} + \lambda(w_{i-n+1}^{i-1})P_{\rm KN}(w_i|w_{i-n+2}^{i-1})$$

$$P_{\mathrm{KN}}(w_{i}|w_{i-n+1}^{i-1}) = \frac{\max(c_{\mathrm{KN}}(w_{i-n+1}^{i}) - d, 0)}{\sum_{v} c_{\mathrm{KN}}(w_{i-n+1}^{i-1}v)} + \lambda(w_{i-n+1}^{i-1})P_{\mathrm{KN}}(w_{i}|w_{i-n+2}^{i-1})$$
Normalizing constant to distribute the probability mass that's been discounted
$$\lambda(w_{i-1}) = \frac{d}{\sum_{v} c(w_{i-1}v)} |\{w : c(w_{i-1}w) > 0\}|$$



 $P_{\rm KN}(w_i|w_{i-n+1}^{i-1}$

Normalizing constant to distribute the probability mass that's been discounted

 $\max(c_{KN}(w_{i-n+1}^{\iota})-d, 0)$

+ $\lambda(w_{i-n+1}^{i-1})P_{KN}(w_i|w_{i-n+2}^{i-1})$

Regular count for the highest-order n-gram, or the number of unique single word contexts for lower-order n-grams

 $P_{_{\rm KN}}(w_i|w_{i-n+1}^{i-1})$

Normalizing constant to distribute the probability mass that's been discounted

 $\max(c_{KN}(w_{i-n+1}^{l}))$

Regular count for the highest-order n-gram, or the number of unique single word contexts for lower-order n-grams

Discounted n-gram probability ... when the recursion terminates, unigrams are interpolated with the uniform distribution (ε = empty string)

$$P_{KN}(w) = \frac{\max(c_{KN}(w) - d, 0)}{\sum_{w'} c_{KN}(w')} + \lambda(\varepsilon) \frac{1}{V}$$

-d, 0)

 $(\lambda(w_{i-n+1}^{i-1})P_{KN}(w_i|w_{i-n+2}^{i-1}))$

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Stupid Backoff

• $S(w) = \frac{c(w)}{w}$

- Gives up the idea of trying to make the language model a true probability distribution ^(C)
- No discounting of higher-order probabilities
- If a higher-order n-gram has a zero count, simply backoff to a lowerorder n-gram, weighted by a fixed weight

•
$$S(w_i | w_{i-k+1}^{i-1}) = \begin{cases} \frac{c(w_{i-k+1}^i)}{c(w_{i-k+1}^{i-1})} & \text{if } c(w_{i-k+1}^i) > 0\\ \lambda S(w_i | w_{i-k+2}^{i-1}) & \text{otherwise} \end{cases}$$

• Terminates in the unigram, which has the probability:

Generally, 0.4 works well (Brants et al., 2007)

Summary: Language Modeling with N-Grams

- N-grams: Sequences of *n* letters
- Language models: Statistical models of language based on observed word or character cooccurrences
- N-gram probabilities can be computed using maximum likelihood estimation
- Language models can be intrinsically evaluated using perplexity
- Unknown words can be handled using <UNK> tokens
- Known words in unseen contexts can be handled using smoothing